



Primordial non-Gaussian features from DBI Galileon inflation

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Abstract We have studied primordial non-Gaussian features of a model of potential-driven single field DBI Galileon inflation. We have computed the bispectrum from the three-point correlation function considering all possible cross correlations between the scalar and tensor modes of the proposed setup. Further, we have computed the trispectrum from a four-point correlation function considering the contribution from contact interaction, and scalar and graviton exchange diagrams in the in-in picture. Finally we have obtained the non-Gaussian consistency conditions from the four-point correlator, which results in partial violation of the *Suyama–Yamaguchi* four-point consistency relation. This further leads to the conclusion that sufficient primordial non-Gaussianities can be obtained from DBI Galileon inflation.

Contents

1 Introduction	1
2 The background model	2
3 Tree level bispectrum analysis	3
3.1 Three-scalar correlation	3
3.2 One-scalar two-tensor correlation	6
3.3 Two-scalar one-tensor correlation	8
3.4 Three-tensor correlation	9
4 Tree level trispectrum analysis from four-scalar correlation	10
4.1 Contact interaction	11
4.2 Scalar exchange	13
4.3 Graviton exchange	14
5 Four-point consistency conditions and violation of Suyama–Yamaguchi relation	16
6 Summary and outlook	17
Appendix	18
A. Functions appearing in three-scalar correlation	18

B. Functions appearing in the one-scalar two-tensor correlation	19
C. Functions appearing in two scalar one tensor correlation	21
D. Functions appearing in three-tensor correlation	24
E. Functions appearing in four-scalar correlator	25
1. Contact interaction	25
2. Scalar exchange	26
3. Graviton exchange	27
References	28

1 Introduction

The physics of the early universe is a very rich area of theoretical physics, for there is a plethora of potential models that solve, at least partially, the well-known problems of the standard cosmological paradigm. Inflationary cosmology is the most successful branch which addressed all of these problems meticulously. This can, however, be explained by several classes of models originating from a proper field theoretic or particle physics framework. But from an observational point view a big issue may crop up in model discrimination and also in the removal of the degeneracy of cosmological parameters obtained from Cosmic Microwave Background (CMB) observations [1–5]. In this context the study of primordial non-Gaussian feature acts as a powerful computational tool to discriminate among inflationary models. In the very recent days the analysis of the bispectrum and the trispectrum derived from the study of primordial features of non-Gaussianity [6–54] from different models of inflation has thus become an intriguing aspect in the context of inflationary model building as well as studies of CMB physics.

Galileon based inflationary models [55–57] and DBI inflationary models [58,59] have both been in vogue for quite some time now. Despite its success, Galileon models generically give rise to unwanted degrees of freedom like ghosts, Laplacian and tachyonic instabilities. Recently, a natural extension to these class of models has been brought forth by

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the present authors [60] in which DBI was clubbed together with Galileon. The framework, called the DBI Galileon framework, consists of a D3 brane in the background of $\mathcal{N} = 1, \mathcal{D} = 4$ SUGRA derived from the D4 brane in $\mathcal{N} = 2, \mathcal{D} = 5$ bulk SUGRA background. The interesting feature of this treaty is that this unwanted debris can be successfully thrown away keeping all the good features of the Galileon intact. In the present paper, our prime objective is to investigate some more interesting features of this rich structure of the DBI Galileon [60], which ultimately results in sufficient non-Gaussianity in this framework. Specifically, we explicitly calculate the bispectrum and the trispectrum from three- and four-point correlation functions by exploiting third- and fourth-order actions. The calculations reveal, along with the feature of large non-Gaussianity, some other interesting results like the partial violation of the *Suyama–Yamaguchi* four-point consistency relation. Subsequently, we demonstrate that, in this framework, it is possible to have a parameter space for both non-Gaussianity and tensor-to-scalar ratio (r) consistent with the combined constraint obtained from the *Planck + WMAP9 + high-L + BICEP2* data [2–5].

The plan of the paper is as follows. First we explore primordial non-Gaussian features from the third-order action through the nonlinear parameter f_{NL} calculated from the bispectrum (in equilateral limit configuration) including all possible scalar-tensor type of cross correlations in the different polarizing modes. Hence from the fourth-order action we derive the expression for the other two nonlinear parameters g_{NL} and τ_{NL} through a trispectrum analysis considering the contribution from contact interaction and scalar and graviton exchange diagrams in the in-in picture. Finally, we explicitly derive the four-point consistency relation from the scalar and graviton exchange diagrams and also find a partial violation of the *standard Suyama–Yamaguchi relation* [61, 62]. We also attempt to give some possible explanations for this violation. We end up with scanning the parameter space for non-Gaussianity and the tensor-to-scalar ratio in the light of *Planck + WMAP9 + high-L + BICEP2* data.

2 The background model

For systematic development of the formalism, let us briefly review from our previous paper [60] how one can construct the effective 4D inflationary potential for the DBI Galileon starting from $\mathcal{N} = 2, \mathcal{D} = 5$ SUGRA along with Gauss–Bonnet correction in the bulk geometry and D4 brane setup leads to an effective $\mathcal{N} = 1, \mathcal{D} = 4$ SUGRA in the D3 brane. Here the total five dimensional model is described by the following action:

$$S_{\text{Total}}^{(5)} = S_{\text{EH}}^{(5)} + S_{\text{GB}}^{(5)} + S_{\text{DBI}}^{(5)} + S_{\text{WZ}}^{(5)} + S_{\text{BSUG}}^{(5)} \quad (2.1)$$

where

$$\begin{aligned} S_{\text{EH}}^{(5)} &= \frac{1}{2\kappa_5^2} \int d^5x \sqrt{-g^{(5)}} [R_{(5)} - 2\Lambda_5], \quad S_{\text{GB}}^{(5)} \\ &= \frac{\alpha^{(5)}}{2\kappa_5^2} \int d^5x \sqrt{-g^{(5)}} [R^{ABCD(5)} R_{ABCD}^{(5)} \\ &\quad - 4R^{AB(5)} R_{AB}^{(5)} + R_{(5)}^2], \\ S_{\text{DBI}}^{(5)} &= -\frac{T_4}{2} \int d^5x \exp(-\Phi) \sqrt{-(\gamma^{(5)} + B^{(5)} + 2\pi\alpha' F^{(5)})}, \\ S_{\text{WZ}}^{(5)} &= -\frac{T_4}{2} \int \sum_{n=0,2,4} \hat{C}_n \wedge \exp(\hat{B}_2 + 2\pi\alpha' F_2)|_4 \text{ form} \\ &= \frac{1}{2} \int d^5x \sqrt{-g^{(5)}} \\ &\quad \times \left\{ \epsilon^{ABCD} \left[\partial_A \Phi^I \partial_B \Phi^J \left(\frac{C_{IJ} B_{KL}}{4T_4} \partial_C \Phi^K \partial_D \Phi^L \right. \right. \right. \\ &\quad \left. \left. + \frac{\pi\alpha' C_{IJ} F_{CD}}{2} + \frac{C_0}{8T_4} B_{IJ} B_{KL} \partial_C \Phi^K \partial_D \Phi^L \right. \right. \\ &\quad \left. \left. + \frac{\pi\alpha' C_0}{2} B_{IJ} F_{CD} \right) + 2\pi^2 \alpha'^2 T_4 C_0 F_{AB} F_{CD} \right. \\ &\quad \left. \left. - T_4 \left(v_0 + \frac{v_4}{\Phi^4} \right) \right] \right\}, \\ S_{\text{BSUG}}^{(5)} &= \frac{1}{2} \int d^5x \sqrt{-g^{(5)}} e_{(5)} \\ &\quad \times \left[-\frac{M_5^3 R^{(5)}}{2} + \frac{i}{2} \bar{\Psi}_{i\bar{m}} \Gamma^{\bar{m}\bar{n}\bar{q}} \nabla_{\bar{n}} \Psi_{\bar{q}}^i - S_{IJ} F_{\bar{m}\bar{n}}^I F^{I\bar{m}\bar{n}} \right. \\ &\quad \left. - \frac{1}{2} g_{\alpha\beta} (D_{\bar{m}} \phi^\mu) (D^{\bar{m}} \phi^\nu) \right. \\ &\quad \left. + \text{Fermionic} + \text{Chern} - \text{Simons} + \text{Pauli mass} \right], \end{aligned} \quad (2.2)$$

where $T_{(4)}$ is the D4 brane tension, α' is the Regge Slope, $\exp(-\Phi)$ is the closed string dilaton and C_0 is the Axion. Here $\gamma^{(5)}$, $B^{(5)}$, and $F^{(5)}$ represent the determinant of the 5D induced metric (γ_{AB}) and the gauge fields (B_{AB} , F_{AB}), respectively. Additionally here v_0 and v_4 represent the constants characterizing the interaction strength between D4– $\bar{D}4$ brane. In the present context 5-dimensional coordinates $X^A = (x^\alpha, y)$, where y parameterizes the extra dimension compactified on the closed interval $[-\pi R, +\pi R]$.

It is useful to introduce the 5D metric in conformal form

$$\begin{aligned} ds_{4+1}^2 &= g_{AB} dX^A dX^B \\ &= \frac{b_0^2}{R^2 \left(\exp(\beta y) + \frac{\Lambda_{(5)} b_0^4}{24R^2} \exp(-\beta y) \right)} \times (ds_4^2 + R^2 \beta^2 dy^2), \end{aligned} \quad (2.3)$$

and $ds_4^2 = g_{\alpha\beta} dx^\alpha dx^\beta$ is FLRW counterpart. The parameter β determines the slope of the warp factor and R represents the compactification radius. Applying dimensional reduction technique via $\mathbf{S}^1/\mathbf{Z}_2$ orbifolding symmetry and using the metric stated in Eq. (2.3) the total effective model for D3

DBI Galileon in background $\mathcal{N} = 1$, $\mathcal{D} = 4$ SUGRA is described by the following action [60]:

$$S = \int d^4x \sqrt{-g^{(4)}} [\hat{K}(\phi, X) - \tilde{G}(\phi, X) \square^{(4)} \phi + \tilde{l}_1 R_{(4)} + \tilde{l}_4 (\mathcal{C}(1) R^{\alpha\beta\gamma\delta(4)} R_{\alpha\beta\gamma\delta}^{(4)} - 4\mathcal{I}(2) R^{\alpha\beta(4)} R_{\alpha\beta}^{(4)} + \mathcal{A}(6) R_{(4)}^2) + \tilde{l}_3], \quad (2.4)$$

where

$$\begin{aligned} \hat{K}(\phi, X) &= -\frac{\tilde{D}}{\tilde{f}(\phi)} \left[\sqrt{1 - 2QX\tilde{f}} - Q_1 \right] \\ &\quad - \tilde{C}_5 \tilde{G}(\phi, X) - 2X\tilde{M}(T, T^\dagger) - V(\phi), \\ \tilde{M}(T, T^\dagger) &= \frac{M(T, T^\dagger)}{2\kappa_{(4)}^2}, \quad M(T, T^\dagger) = \frac{\sqrt{2}\beta R^2}{(T + T^\dagger)}, \\ \tilde{D} &= \frac{D}{2\kappa_{(4)}^2}, \\ \tilde{G}(\phi, X) &= \left(\frac{\tilde{g}(\phi)k_1\tilde{C}_4}{2(1 - 2\tilde{f}(\phi)Xk_2)} \right), \\ \tilde{g}(\phi) &= \tilde{g}_0 + \tilde{g}_2\phi^2, \quad \tilde{f}(\phi) \simeq \frac{1}{(\tilde{f}_0 + \tilde{f}_2\phi^2 + \tilde{f}_4\phi^4)} \\ \tilde{l}_1 &= \left\{ \frac{1}{2\kappa_{(4)}^2} \left[1 + \frac{\alpha_{(4)}}{R^2\beta^2} (24\mathcal{I}(2) - 24\mathcal{A}(9) - 16\mathcal{A}(10)) \right] \right. \\ &\quad \left. - \frac{\alpha_{(4)}\mathcal{C}(2)}{\kappa_{(4)}^2 R^2\beta^2} \right\}, \quad \tilde{l}_4 = \frac{\alpha_{(4)}}{2\kappa_{(4)}^2}, \\ \tilde{l}_3 &= \frac{1}{2\kappa_{(4)}^2} \left[\frac{\alpha_{(4)}}{R^4\beta^4} (24\mathcal{C}(4) - 144\mathcal{I}(4) - 64\mathcal{A}(5) + 144\mathcal{A}(7) \right. \\ &\quad \left. + 64\mathcal{A}(8) + 192\mathcal{A}(11)) - \frac{3M_5^3\beta b_0^6}{2\kappa_{(4)}^2 M_{\text{PL}}^2 R^5} \mathcal{I}(1) \right], \end{aligned} \quad (2.5)$$

where $\alpha_{(4)}, \tilde{l}_1, \tilde{l}_3, \tilde{l}_4$ are effective 4D couplings and $\kappa_{(4)}$ be the gravitational coupling strength. Here X represents the 4D kinetic term after dimensional reduction given by $X := -\frac{1}{2}g_{\mu\nu}\partial^\mu\phi\partial^\nu\phi$. In this context (T, T^\dagger) are the four dimensional background SUGRA moduli fields which are constant after dimensional reduction.

The one-loop corrected Coleman–Weinberg potential is given by [60]

$$V(\phi) = \sum_{m=-2, m \neq -1}^2 C_{2m} \left[1 + D_{2m} \ln \left(\frac{\phi}{M} \right) \right] \phi^{2m}, \quad (2.6)$$

where $D_0 = 0$ and the other constants are functions of the effective brane tension for the D3 brane and constant moduli in 4D. Hence using Eq. (2.4) the modified Friedman equation in the presence of effective 4D Gauss–Bonnet coupling can be expressed as [60]:

$$H^4 = \frac{\Lambda_{(4)} + 8\pi G_{(4)}\rho_\phi}{\tilde{g}_1} \approx \frac{\Lambda_{(4)} + 8\pi G_{(4)}V(\phi)}{\tilde{g}_1}, \quad (2.7)$$

where ρ_ϕ plays the role of energy density of the inflation in 4D effective theory, \tilde{g}_1 represents the effective 4D Gauss–Bonnet coupling dependent function on FLRW background which can be expressed in terms of the brane tension of D3 brane and $\Lambda_{(4)}$ is the 4D effective cosmological constant. It is important to note that in the 4D effective action as stated in Eq. (2.4), the contribution of higher curvature effective Gauss–Bonnet like correction term is dominant compared to Ricci scalar. More precisely one can interpret this to be a non-perturbative solution of the effective field theory where the effective coupling parameter $\tilde{l}_4 \gg \tilde{l}_1$. Consequently the effective Friedmann equation in 4D takes a non-trivial form in the high energy regime, where energy density of the inflaton $\rho_\phi \approx V(\phi) \gg \tilde{g}_1$ of $D3 - \bar{D}3$ system. Here Eq. (2.7) also implies that within our prescribed setup the non-perturbative regime of effective field theory cannot be able to produce the well-known solutions of GR in the low energy limiting situation where $\rho_\phi \approx V(\phi) \ll \tilde{g}_1$. But in the perturbative regime of the effective theory the situation is completely different compared the non-perturbative case. In the regime where the effective coupling parameter $\tilde{l}_4 \ll \tilde{l}_1$, it is possible to get back the known solution of GR. In literature it usually identified to be the low energy regime, where the inflaton energy density, $\rho_\phi \approx V(\phi) \ll \tilde{g}_1$ in $D3 - \bar{D}3$ system. But in the high energy regime, where $\rho_\phi \approx V(\phi) \gg \tilde{g}_1$, it is not possible to realize the essence of the higher curvature terms through Friedmann equations, which will finally control the cosmological dynamics in a nontrivial manner. For more details see Ref. [60], where the Friedmann equations are derived in detail.

3 Tree level bispectrum analysis

3.1 Three-scalar correlation

To calculate the scalar bispectrum for D3 DBI Galileon we consider here the third-order action up to total derivatives. Using the uniform field gauge analysis the third-order action for three scalar interaction can be written as

$$\begin{aligned} S_{\zeta\zeta\zeta} &= \int dt d^3x \left\{ a^3 \bar{C}_1 M_{\text{PL}}^2 \zeta \dot{\zeta}^2 \right. \\ &\quad + a \bar{C}_2 M_{\text{PL}}^2 \zeta (\partial\zeta)^2 + a^3 \bar{C}_3 M_{\text{PL}} \dot{\zeta}^3 \\ &\quad + a^3 \bar{C}_4 \dot{\zeta} (\partial_i \zeta) (\partial_i \tilde{\chi}) + a^3 \left(\frac{\bar{C}_5}{M_{\text{PL}}^2} \right) \partial^2 \zeta (\partial \tilde{\chi})^2 \\ &\quad \left. \times a \bar{C}_6 \dot{\zeta}^2 \partial^2 \zeta + \left(\frac{\bar{C}_7}{a} \right) [\partial^2 \zeta (\partial\zeta)^2 - \zeta \partial_i \partial_j (\partial_i \zeta) (\partial_j \zeta)] \right\} \end{aligned}$$

$$+ a \frac{\bar{C}_8}{M_{\text{PL}}} [\partial^2 \zeta \partial_i \zeta \partial_j \tilde{\chi} - \zeta \partial_i \partial_j (\partial_i \zeta) (\partial_j \tilde{\chi})] + \mathcal{R} \frac{\delta \mathcal{L}_2}{\delta \zeta} \Big|_1 \Big\}, \quad (3.1)$$

where

$$\frac{\delta \mathcal{L}_2}{\delta \zeta} \Big|_1 = -2 \left[\frac{d}{dt} (a^3 Y_S \dot{\zeta}) - a Y_S c_s^2 \partial^2 \zeta \right] \quad (3.2)$$

can be calculated from the second-order action [60]

$$(S^{(4)})_{\zeta\zeta} = \int dt d^3 x a^3 Y_S \left[\dot{\zeta}^2 - \frac{c_s^2}{a^2} (\partial \zeta)^2 \right]. \quad (3.3)$$

Here \bar{C}_i ($i = 1, 2, 3, \dots, 8$) are dimensionless coefficients defined as

$$\begin{aligned} \bar{C}_1 &= \frac{Y_S}{M_{\text{PL}}^2} \left[3 - \frac{L_1 H}{c_s^2} \left(3 + \frac{\dot{Y}_S}{H Y_S} \right) + \frac{d}{dt} \left(\frac{L_1}{c_s^2} \right) \right], \\ \bar{C}_2 &= \left[1 + \frac{1}{a} \frac{d}{dt} (a L_1 \{Y_S - t_1\}) \right], \\ \bar{C}_3 &= \frac{L_1}{M_{\text{PL}}} \left[L_1 (L_1 a_1 + a_3) + a_{12} + (a_9 + L_1 a_4) \frac{Y_S}{t_1} + \frac{Y_S}{c_s^2} \right], \\ \bar{C}_4 &= -\frac{Y_S}{2t_1} \left\{ 1 + 2t_1 \left[\frac{d}{dt} \left(\frac{A_5}{t_1^2} \right) - \frac{3H A_5}{t_1^2} \right] \right\}, \\ \bar{C}_5 &= \frac{M_{\text{PL}}^2}{2t_1^2} \left[\frac{3M_{\text{PL}}^2}{2} (1 - H L_1) \right] - \frac{M_{\text{PL}}^2}{2} \frac{d}{dt} \left(\frac{A_5}{t_1^2} \right), \\ \bar{C}_6 &= L_1^2 [2M_{\text{PL}}^2 - L_1 a_4], \\ \bar{C}_7 &= \frac{L_1^2 M_{\text{PL}}^2 (1 - H L_1)}{6} - \frac{c_s^2 Y_S L_1^2 M_{\text{PL}}^2}{2t_1} + \frac{M_{\text{PL}}^2}{6} \frac{d}{dt} (L_1^3), \\ \bar{C}_8 &= M_{\text{PL}} \left\{ \frac{L_1 M_{\text{PL}}^2}{t_1} (H L_1 - 1) + \frac{c_s^2 Y_S L_1 M_{\text{PL}}^2}{t_1^2} \right\} \end{aligned} \quad (3.4)$$

and the coefficient of $\frac{\delta \mathcal{L}_2}{\delta \zeta} \Big|_1$ involving spatial and time derivatives in Eq. (3.1) is defined by the following expression:

$$\begin{aligned} \mathcal{R} &= \frac{A_5}{t_1^2} \{ (\partial_k \zeta) (\partial_k \tilde{\chi}) - \partial^{-2} \partial_i \partial_j [(\partial_i \zeta) (\partial_j \tilde{\chi})] \} \\ &+ p_1 \zeta \dot{\zeta} - \frac{A_5 L_1}{2t_1 a^2} \{ (\partial \zeta)^2 - \partial^{-2} \partial_i \partial_j [(\partial_i \zeta) (\partial_j \zeta)] \}. \end{aligned} \quad (3.5)$$

In this context $\mathcal{R} \rightarrow 0$ as $k \rightarrow 0$ at large scale. Additionally

$$L_1 = \left(\frac{M_{\text{PL}}^2}{H M_{\text{PL}}^2 - \dot{\phi} X \tilde{G}_X} \right), \quad \tilde{\chi} = \partial^{-2} (Y_S \dot{\zeta}), \quad A_3 = 2Y_S,$$

$$A_5 = -\frac{L_1 M_{\text{PL}}^2}{2},$$

$$Y_S = \frac{t_1 (4t_1 t_3 + 9t_2^2)}{3t_2^2}, \quad c_s^2 = \frac{3(2H t_2 t_1^2 - t_4 t_2^2 - 2t_1^2 t_2)}{t_1 (4t_1 t_3 + 9t_2^2)},$$

$$t_1 = \tilde{l}_1, \quad t_2 = (2H \tilde{l}_1 - 2\dot{\phi} X \tilde{G}_X),$$

$$\begin{aligned} t_3 &= -9\tilde{l}_1 H^2 + 3(X \hat{K}_X + 2X^2 \hat{K}_{XX}) \\ &+ 18H \dot{\phi} (2X \tilde{G}_X + X^2 \tilde{G}_{XX}), \\ a_1 &= 3M_{\text{PL}}^2 H^2 - X \hat{K}_X - 4X^2 \hat{K}_{XX} \\ &- \frac{4X^3}{3} X \hat{K}_{XXX} - 2H \dot{\phi} (10X \tilde{G}_X + 11X^2 \tilde{G}_{XX} \\ &+ 2X^3 \tilde{G}_{XXX}) + 2X \tilde{G}_\phi + \frac{14X^2}{3} \tilde{G}_{\phi X} + \frac{4X^3}{3} \tilde{G}_{\phi XX}, \\ a_3 &= -3a_4 = -3[2M_{\text{PL}}^2 H - 2\dot{\phi} (2X \tilde{G}_X + X^2 \tilde{G}_{XX})], \\ a_9 &= -\frac{2}{3} a_{12} = -2M_{\text{PL}}^2. \end{aligned} \quad (3.6)$$

It is important to mention here that for scalar and tensor modes *ghosts* and *Laplacian* instabilities can be avoided iff $c_s^2 > 0$, $Y_S > 0$. Throughout the paper we use the required parameters from [60] to compute the bispectrum and trispectrum.

Now following the prescription of the *in-in* formalism in the interacting picture the *three-point correlation function* for the quasi-exponential limit, after some trivial algebra, look:

$$\begin{aligned} \langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \rangle &= -i \sum_{j=1}^8 \int_{-\infty}^0 d\eta a \\ &\times \langle 0 | [\zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3), (H_{\text{int}}^{(j)}(\eta))_{\zeta\zeta\zeta}] | 0 \rangle \\ &= (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) \mathcal{B}_{\zeta\zeta\zeta}(\vec{k}_1, \vec{k}_2, \vec{k}_3), \end{aligned} \quad (3.7)$$

where the total Hamiltonian in the interaction picture can be expressed in terms of the third-order Lagrangian density as $(H_{\text{int}}(\eta))_{\zeta\zeta\zeta} = \sum_{j=1}^8 (H_{\text{int}}^{(j)}(\eta))_{\zeta\zeta\zeta} = -\int d^3x (\mathcal{L}_3)_{\zeta\zeta\zeta}$.

Throughout this article we use the Bunch–Davies mode function as

$$\begin{aligned} u_m(\eta, k) &= \frac{\sqrt{-k\eta c_m}}{a\sqrt{2Y_m}} \mathcal{H}_{\nu_m}^{(1)}(-k\eta c_m) \\ &\rightarrow \frac{(-kc_m\eta)^{\frac{1}{2}-\nu_m} \exp(i[v_m - \frac{1}{2}]\frac{\pi}{2}) 2^{\nu_m-\frac{3}{2}}}{2a\sqrt{Y_m c_m k}} \left(\frac{\Gamma(\nu_m)}{\Gamma(\frac{3}{2})} \right), \end{aligned} \quad (3.8)$$

with $m = (S[\text{scalar}], T[\text{tensor}])$. Moreover, following the momentum dependent ansatz given in [45, 46, 63] the *bispectrum* $\mathcal{B}_{\zeta\zeta\zeta}(\vec{k}_1, \vec{k}_2, \vec{k}_3)$ is defined as

$$\mathcal{B}_{\zeta\zeta\zeta}(\vec{k}_1, \vec{k}_2, \vec{k}_3) = \frac{(2\pi)^4 \mathcal{P}_\zeta^2}{\prod_{i=1}^3 k_i^3} \mathcal{A}_{\zeta\zeta\zeta}(\vec{k}_1, \vec{k}_2, \vec{k}_3) = \frac{6}{5} f_{\text{NL};1} P_\zeta^2 \quad (3.9)$$

where the symbol 1 is used for the three-scalar correlation. Here $\mathcal{A}_{\zeta\zeta\zeta}(\vec{k}_1, \vec{k}_2, \vec{k}_3)$ is the *shape function* for bispectrum and P_ζ^2 is used for normalization of E-mode polarization expressed in terms of the new combination of the cyclic permutations of two-point correlation functions given by

$$P_\zeta^2 = P_\zeta(k_1) P_\zeta(k_2) + P_\zeta(k_2) P_\zeta(k_3) + P_\zeta(k_3) P_\zeta(k_1). \quad (3.10)$$

The *Power spectra* for scalar ($P_\zeta(k)$) and tensor modes ($P_T(k)$) at the horizon crossing can be written as

$$P_\zeta(k) = \left(2^{2\nu_s-3} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^2 \frac{(1-\epsilon_V - s_V^S)^2 \sqrt{V(\phi)}}{8\pi^2 Y_S c_s^3 \sqrt{\tilde{g}_1} M_{\text{PL}}} \right), \quad (3.11)$$

$$P_T(k) = \left(2^{2\nu_T-3} \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{(1-\epsilon_V - s_V^T)^2 \sqrt{V(\phi)}}{2\pi^2 Y_T c_T^3 \sqrt{\tilde{g}_1} M_{\text{PL}}} \right).$$

Here for the tensor modes we use $(P_T(k))_{ij;kl} = |u_h(\eta, k)|^2 \mathcal{N}_{ij;kl}$, $P_T(k) = (P_T(k))_{ij;ij}$ with the following helicity/spin dependent normalization factor: $\mathcal{N}_{ij;kl} = \sum_\lambda e_{ij}^\lambda(\vec{k}) e_{kl}^{\dagger(\lambda)}(\vec{k})$.

In this context f_{NL} represents the nonlinear parameter carrying the signature of primordial non-Gaussianities of the curvature perturbation in bispectrum. The explicit form of f_{NL} characterizing the bispectrum can be expressed as

$$f_{\text{NL};1} = \frac{10}{3 \sum_{i=1}^3 k_i^3} \left(\frac{k_1 k_2 k_3}{2K^3} \right)^{n_\zeta-1} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^2$$

$$\times \left\{ \bar{C}_1 \left[\frac{3}{4} \mathcal{I}_1(n_\zeta - 1) - \frac{3-\epsilon_V}{4c_s^2} \left(\frac{1+Y_S}{1+\epsilon_V} \right)^2 \mathcal{I}_1(\tilde{\nu}) \right] \right.$$

$$+ \frac{3(1-\epsilon_V - s_V^S)}{2Y_S} \left[\mathcal{F}_3 \mathcal{I}_3(n_\zeta - 1) + \frac{\mathcal{E}_3}{c_s^2} \mathcal{I}_3(\tilde{\nu}) \right]$$

$$+ \frac{\bar{C}_4}{8} \mathcal{I}_4(\tilde{\nu}) + \frac{\bar{C}_5 Y_S}{4c_s^2} \mathcal{I}_5(\tilde{\nu})$$

$$+ \frac{3(1-\epsilon_V - s_V^S)^2}{Y_S} \left[\mathcal{F}_6 \mathcal{I}_6(n_\zeta - 1) + \frac{\mathcal{E}_6}{c_s^2} \mathcal{I}_6(\tilde{\nu}) \right]$$

$$\left. + \frac{\bar{C}_7(1-\epsilon_V - s_V^S)^2}{2Y_S c_s^2} \mathcal{I}_7(\tilde{\nu}) + \frac{\bar{C}_8(1-\epsilon_V - s_V^S)}{8c_s^2} \mathcal{I}_8(\tilde{\nu}) \right\}, \quad (3.12)$$

where the functional form of the momentum dependent functions $\mathcal{I}_i(x) \forall i$ are explicitly mentioned in Appendix B. From the coefficients of $\mathcal{I}_i(\tilde{\nu})$ with $i = 1, 3, 5, 7, 8$ it seems that the non-Gaussian parameter $f_{\text{NL};1}$ is inverse proportional to the sound speed square for the scalar mode. But these coefficients are not solely characterized by the sound speed for the scalar mode since they depend on other factors like (1) effective Gauss–Bonnet coupling ($\alpha_{(4)}$) and (2) higher-order interaction between the graviton and the DBI Galileon in the presence of a quadratic correction of gravity in the Einstein–Hilbert action. Additionally in this context counter terms which appears as the coefficients of $\mathcal{I}_i(n_\zeta - 1)$ with $i = 1, 3, 6$, and $\mathcal{I}_4(\tilde{\nu})$ originated from the effective Gauss–Bonnet coupling ($\alpha_{(4)}$) and higher-order interaction between the graviton (via a Gauss–Bonnet correction) and the DBI Galileon degrees of freedom in the D3 brane in the background of four dimensional $\mathcal{N} = 1$ SUGRA multiplet play a very crucial role in this context. In $\alpha_{(4)} \neq 0$ limit such counter terms and dependence on the interaction between the graviton and the higher derivative DBI Galileon cannot be negligible in the slow-roll limit.

Consequently, depending on the signature and the strength of the effective Gauss–Bonnet coupling three situations arise: (1) the counter terms drive other terms, (2) the counter terms and other terms are tuned in such a way that the system is in equilibrium with respect to the sound speed and (3) the sound speed dominated terms win the war.

Here the second situation is not physically interesting and the third situation leads to the trivial feature of the DBI Galileon. Only the nontrivial features comes from the first situation in the context of single field DBI Galileon inflation.

In Eq. (3.12) we have defined $K = k_1 + k_2 + k_3$, $x = (n_\zeta - 1, \tilde{\nu})$, and

$$\tilde{\nu} := \left(\frac{s_V^S - 2\epsilon_V}{1 - \epsilon_V - s_V^S} \right), \quad n_\zeta - 1 = (3 - 2\nu_s) = - \left(\frac{2\epsilon_V + s_V^S + \delta_V}{1 - \epsilon_V - s_V^S} \right)$$

$$\mathcal{F}_3 := - \frac{Y_S(1+Y_S)}{1+\epsilon_V} \left[1 + 2 \frac{Y_S - \epsilon_V + (1+Y_S)\rho_3}{1+\epsilon_V} + 2\mathcal{T}_3 \right],$$

$$\frac{\dot{\phi} X^2 \tilde{G}_{XX}}{H} = \left(\rho_3 + \frac{\rho_4}{c_s^2} \right), \quad \frac{\nu_s}{\Sigma_G} := \left(\mathcal{T}_3 + \frac{\mathcal{T}_4}{c_s^2} \right), \quad (3.13)$$

$$\mathcal{E}_3 := - \frac{Y_S(1+Y_S)}{1+\epsilon_V} \left[2\mathcal{T}_4 - \frac{1+Y_S}{1+\epsilon_V} (1 - 2\rho_4) \right],$$

$$\mathcal{F}_6 := \frac{2(1+Y_S)^3}{(1+\epsilon_V)^3} \left[\frac{Y_S - \epsilon_V}{1+Y_S} + \rho_3 \right], \quad \mathcal{E}_6 := \frac{2\rho_4(1+Y_S)^3}{(1+\epsilon_V)^3}$$

with the four new constants $\rho_3, \rho_4, \mathcal{T}_3, \mathcal{T}_4$. In the present context $s_V^S = \frac{\dot{c}_s}{H c_s}$ is an extra slow-roll parameter appearing due to the sound speed, $c_s \neq 1$ as defined in [60]. For the numerical estimation we have further used the *equilateral configuration* ($k_1 = k_2 = k_3 = k$ and $K = 3k$) in which the nonlinear parameter f_{NL} can be simplified to the following form:

$$f_{\text{NL};1}^{\text{equil}} = \frac{10}{9k^3} \left(\frac{1}{54} \right)^{n_\zeta-1} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^2$$

$$\times \left\{ \left(3 \left(1 - \frac{1}{c_s^2} \right) - \frac{Y_S \delta_V}{c_s^2} + \frac{Y_S^2}{c_s^2} - \frac{2Y_S s_V^S}{c_s^2} \right) \right.$$

$$\times \left[\frac{3}{4} \mathcal{I}_1^{\text{equil}}(n_\zeta - 1) - \frac{3-\epsilon_V}{4c_s^2} \left(\frac{1+Y_S}{1+\epsilon_V} \right)^2 \mathcal{I}_1^{\text{equil}}(\tilde{\nu}) \right]$$

$$+ \frac{3(1-\epsilon_V - s_V^S)}{2Y_S} \left[\mathcal{F}_3 \mathcal{I}_3^{\text{equil}}(n_\zeta - 1) + \frac{\mathcal{E}_3}{c_s^2} \mathcal{I}_3^{\text{equil}}(\tilde{\nu}) \right]$$

$$- \frac{1}{8} \left[\frac{Y_S}{2} + \frac{Y_S}{2} (3 - Y_S) \right] \mathcal{I}_4^{\text{equil}}(\tilde{\nu})$$

$$+ \frac{Y_S}{4c_s^2} \left(\frac{4\epsilon_V - Y_S(3 - \epsilon_V)}{4(1+\epsilon_V)} \right) \mathcal{I}_5^{\text{equil}}(\tilde{\nu})$$

$$+ \frac{3(1-\epsilon_V - s_V^S)^2}{Y_S} \left[\mathcal{F}_6 \mathcal{I}_6^{\text{equil}}(n_\zeta - 1) + \frac{\mathcal{E}_6}{c_s^2} \mathcal{I}_6^{\text{equil}}(\tilde{\nu}) \right]$$

$$- \frac{(1-\epsilon_V - s_V^S)^2 (1+Y_S)^2 (Y_S - \epsilon_V)}{2Y_S c_s^2 (1+\epsilon_V)^3} \mathcal{I}_7^{\text{equil}}(\tilde{\nu})$$

$$\left. + \frac{(1+Y_S)(Y_S - \epsilon_V)(1-\epsilon_V - s_V^S)}{4c_s^2 (1+\epsilon_V)^2} \mathcal{I}_8^{\text{equil}}(\tilde{\nu}) \right\}. \quad (3.14)$$

Now using the tensor-to-scalar ratio at the pivot scale k_* :

$$r = \left(16.2^{2(\nu_T - \nu_s)} \left| \frac{\Gamma(\nu_T)}{\Gamma(\nu_s)} \right|^2 \left(\frac{1 - \epsilon_V - s_V^T}{1 - \epsilon_V - s_V^S} \right)^2 c_s \epsilon_s \times \left[1 - \frac{3}{2} \mathcal{O}(\epsilon_T^2) \right] \right)^*, \quad (3.15)$$

the sound speed c_s can be eliminated from Eq. (3.14) also.

Here $s_V^T = \frac{\dot{c}_T}{H c_T}$ appears due to the sound speed, $c_T \neq 1$. See [60] for the details. The numerical value of $f_{\text{NL};1}^{\text{equil}}$ in the equilateral limit is obtained from our setup as $4 < f_{\text{NL};1}^{\text{equil}} < 7$ within the window for tensor-to-scalar ratio $0.213 < r < 0.250$ [60]. This is extremely interesting result as it is different from other class of DBI models. The most impressing fact is that the upper bound of $f_{\text{NL};1}^{\text{equil}}$ in the quasi-exponential limit is in good agreement with the combined constraint obtained from the *Planck* + *WMAP9* + *high-L* + *BICEP2* [2–5] data.

3.2 One-scalar two-tensor correlation

After applying the gauge fixing condition to uniform gauge the one-scalar and two tensor interaction can be represented by the following third-order action:

$$S_{\zeta hh} = \int dt d^3x a^3 \left\{ \mathcal{F}_1 \zeta \dot{h}_{ij}^2 + \frac{\tilde{\mathcal{F}}_2}{a^2} \zeta h_{ij,k} h_{ij,k} + \tilde{\mathcal{F}}_3 \psi_{,k} \dot{h}_{ij} h_{ij,k} + \mathcal{F}_4 \dot{\zeta} \dot{h}_{ij}^2 + \frac{\tilde{\mathcal{F}}_5}{a^2} \partial^2 \zeta \dot{h}_{ij}^2 + \tilde{\mathcal{F}}_6 \psi_{,ij} \dot{h}_{ik} \dot{h}_{jk} + \frac{\tilde{\mathcal{F}}_7}{a^2} \zeta_{,ij} \dot{h}_{ik} \dot{h}_{jk} \right\}, \quad (3.16)$$

where the dimensionful coefficients \mathcal{F}_i ($i = 1, 2, \dots, 7$) are defined as

$$\begin{aligned} \tilde{\mathcal{F}}_1 &= 3Y_T \left[1 - \frac{H L_1 Y_T}{c_T^2} + \frac{Y_T}{3} \frac{d}{dt} \left(\frac{L_1}{c_T^2} \right) \right], \\ \tilde{\mathcal{F}}_2 &= Y_s c_s^2, \quad \tilde{\mathcal{F}}_3 = -2Y_s, \\ \tilde{\mathcal{F}}_4 &= \frac{L_1}{c_T^2} \left(Y_T^2 - \hat{K}_{XX} \right) + 2\sigma \\ &\quad \times \left[\frac{Y_s}{Y_T} - 1 - \frac{H L_1 Y_T}{c_T^2} \left(6 + \frac{\dot{Y}_s}{H Y_s} \right) \right] + 2Y_T^2 \frac{d}{dt} \left(\frac{\sigma L_1}{Y_T c_T^2} \right), \\ \tilde{\mathcal{F}}_5 &= 2\sigma Y_T L_1 \left(\frac{c_s^2}{c_T^2} - 1 \right), \quad \tilde{\mathcal{F}}_6 = -\frac{4\sigma Y_s}{Y_T}, \\ \tilde{\mathcal{F}}_7 &= 4\sigma Y_T L_1, \end{aligned} \quad (3.17)$$

where we use $\sigma = \dot{\phi} X G_{5X}$. Now following the prescription of the *in-in* formalism in the interaction picture *three-point one scalar two-tensor correlation function* can be expressed in the following form:

$$\begin{aligned} \langle \zeta(\vec{k}_1) h_{ij}(\vec{k}_2) h_{kl}(\vec{k}_3) \rangle &= -i \sum_{q=1}^7 \int_{-\infty}^0 d\eta a \\ &\quad \times \langle 0 | [\zeta(\vec{k}_1) h_{ij}(\vec{k}_2) h_{kl}(\vec{k}_3), ([H_{\text{int}}^{(q)}(\eta)]_{ij;kl})_{\zeta hh}] | 0 \rangle \\ &= (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) \{ B_{\zeta hh} \}_{ij;kl}(\vec{k}_1, \vec{k}_2, \vec{k}_3), \end{aligned} \quad (3.18)$$

where the total Hamiltonian in the interaction picture can be expressed in terms of the third-order Lagrangian density as $([H_{\text{int}}(\eta)]_{ij;kl})_{\zeta hh} = \sum_{q=1}^7 ([H_{\text{int}}^{(q)}(\eta)]_{ij;kl})_{\zeta hh} = -\int d^3x [(\mathcal{L}_3)_{\zeta hh}]_{ij;kl}$. Moreover, the *cross bispectrum* $\{ B_{\zeta hh} \}_{ij;kl}(\vec{k}_1, \vec{k}_2, \vec{k}_3)$ is defined as

$$\begin{aligned} \{ B_{\zeta hh} \}_{ij;kl}(\vec{k}_1, \vec{k}_2, \vec{k}_3) &= \frac{(2\pi)^4 \mathcal{P}_u^2}{\prod_{i=1}^3 k_i^3} (\mathcal{A}_{\zeta hh})_{ij;kl}(\vec{k}_1, \vec{k}_2, \vec{k}_3) \\ &= \frac{6}{5} [f_{\text{NL};2}]_{ij;kl}^u P_u^2 \end{aligned} \quad (3.19)$$

where the symbol ; 2 stands for one scalar two-tensor correlation. Here $(\mathcal{A}_{\zeta hh})_{ij;kl}(\vec{k}_1, \vec{k}_2, \vec{k}_3)$ is the *shape function* for bispectrum and the polarization indices are $u = 1$ (E – mode), 2 (E \otimes B – mode), 3 (B – mode). We adopt the following normalization depending on the polarization in which we are interested:

$$P_u^2 = \begin{cases} P_\zeta(k_1) P_\zeta(k_2) + P_\zeta(k_2) P_\zeta(k_3) + P_\zeta(k_3) P_\zeta(k_1) \\ \quad : u = 1 \text{ (E – mode)} \\ P_\zeta(k_1) P_h(k_2) + P_\zeta(k_2) P_h(k_3) + P_\zeta(k_3) P_h(k_1) \\ \quad : u = 2 \text{ (E } \otimes \text{ B mode)} \\ P_h(k_1) P_h(k_2) + P_h(k_2) P_h(k_3) + P_h(k_3) P_h(k_1) \\ \quad : u = 3 \text{ (B – mode)}. \end{cases} \quad (3.20)$$

Consequently $[f_{\text{NL};2}]_{ij;kl}^u$ represents the nonlinear parameter which carries the signature of primordial non-Gaussianities of the one-scalar two tensor interaction. The explicit form of $[f_{\text{NL};2}]_{ij;kl}^u$ characterizing the bispectrum can be calculated as

$$\begin{aligned}
[f_{\text{NL};2}]_{ij;kl}^u &= \frac{10Q_u^{\text{POL}} \left(\frac{3}{2} - v_T\right)^2 \underline{K}^{4v_T+2v_s-9} \left[\text{Cos}\left(\left[v_s - \frac{1}{2}\right] \frac{\pi}{2}\right)\right]^{\frac{1}{3}} \left[\text{Cos}\left(\left[v_T - \frac{1}{2}\right] \frac{\pi}{2}\right)\right]^{\frac{2}{3}}}{3 \sum_{i=1}^3 k_i^3 \frac{c_s^{2v_s-3} c_T^{4v_T-6} (k_1)^{v_s} (k_2 k_3)^{v_T}}{Y_S Y_T^2 c_T^4 c_s^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3}} \\
&\times \left(2^{2v_s+4v_T-12} \left|\frac{\Gamma(v_s)}{\Gamma(\frac{3}{2})}\right|^2 \left|\frac{\Gamma(v_T)}{\Gamma(\frac{3}{2})}\right|^4 \frac{(1-\epsilon_V - s_V^S)^2 (1-\epsilon_V - s_V^T)^4 V^{\frac{3}{2}}(\phi)}{Y_S Y_T^2 c_T^4 c_s^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3}\right) \\
&\times [32\tilde{\mathcal{F}}_1(\nabla_1)_{ij;kl}^u + 4\tilde{\mathcal{F}}_2(\nabla_2)_{ij;kl}^u + 2(\tilde{\mathcal{F}}_3(\nabla_3)_{ij;kl}^u + \tilde{\mathcal{F}}_4(\nabla_4)_{ij;kl}^u + \tilde{\mathcal{F}}_5(\nabla_5)_{ij;kl}^u + \tilde{\mathcal{F}}_6(\nabla_6)_{ij;kl}^u + \tilde{\mathcal{F}}_7(\nabla_7)_{ij;kl}^u)] \quad (3.21)
\end{aligned}$$

with polarization index $u = 1(\text{E}), 2(\text{E} \otimes \text{B}), 3(\text{B})$. The functional form of the coefficients $(\nabla_i)_{ij;kl}^u \forall i$ are explicitly mentioned in Appendix B. In this context we define $\underline{K} := c_s k_1 + c_T (k_2 + k_3)$.

The overall normalization factor for the three types of polarization can be expressed as

$$Q_u^{\text{POL}} = \begin{cases} 8 & : u = 1 \text{ (E - mode)} \\ 128 & : u = 2 \text{ (E} \otimes \text{B mode)} \\ 2048 & : u = 3 \text{ (B - mode)}. \end{cases} \quad (3.22)$$

Further, to make the computation simpler without losing any essential information we reduce the complete set in terms of the two-polarization (helicity) mode instead of four complicated tensor indices. For this purpose let us define the reduced physical quantity:

$$\bigoplus^{\lambda}(\vec{k}) = h_{ij}(\vec{k}) e_{ij}^{\dagger(\lambda)} \quad (3.23)$$

in terms of which the one-scalar two-tensor correlation is defined as

$$\begin{aligned}
&\langle \zeta(\vec{k}_1) \bigoplus^{\lambda_2}(\vec{k}_2) \bigoplus^{\lambda_3}(\vec{k}_3) \rangle \\
&= (2\pi)^3 \delta(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) B_{(\zeta hh)}^{(\lambda_1; \lambda_2)}(\vec{k}_1, \vec{k}_2, \vec{k}_3). \quad (3.24)
\end{aligned}$$

where the *cross reduced bispectrum* is defined as

$$\begin{aligned}
B_{(\zeta hh)}^{(\lambda_2; \lambda_3)}(\vec{k}_1, \vec{k}_2, \vec{k}_3) &= \frac{(2\pi)^4 \mathcal{P}_u^2}{\prod_{i=1}^3 k_i^3} \mathcal{A}_{(\zeta hh)}^{(\lambda_2; \lambda_3)} \\
&= \frac{6}{5} [f_{\text{NL};2}]^{u; (\lambda_2; \lambda_3)} P_u^2. \quad (3.25)
\end{aligned}$$

Applying the basis transformation the explicit form of $[f_{\text{NL};2}]^{(\lambda_2; \lambda_3)}$ characterizing the crossed bispectrum can be written as

$$\begin{aligned}
[f_{\text{NL};2}]^{u; (\lambda_2; \lambda_3)} &= \frac{10Q_u^{\text{POL}} \left(\frac{3}{2} - v_T\right)^2 \underline{K}^{4v_T+2v_s-9} \left[\text{Cos}\left(\left[v_s - \frac{1}{2}\right] \frac{\pi}{2}\right)\right]^{\frac{1}{3}} \left[\text{Cos}\left(\left[v_T - \frac{1}{2}\right] \frac{\pi}{2}\right)\right]^{\frac{2}{3}}}{3 \sum_{i=1}^3 k_i^3 \frac{c_s^{2v_s-3} c_T^{4v_T-6} (k_1)^{v_s} (k_2 k_3)^{v_T}}{Y_S Y_T^2 c_T^4 c_s^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3}} \\
&\times \left(2^{2v_s+4v_T-12} \left|\frac{\Gamma(v_s)}{\Gamma(\frac{3}{2})}\right|^2 \left|\frac{\Gamma(v_T)}{\Gamma(\frac{3}{2})}\right|^4 \frac{(1-\epsilon_V - s_V^S)^2 (1-\epsilon_V - s_V^T)^4 V^{\frac{3}{2}}(\phi)}{Y_S Y_T^2 c_T^4 c_s^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3}\right) \\
&\times [32\tilde{\mathcal{F}}_1(\nabla_1)^{u; \lambda_2; \lambda_3} + 4\tilde{\mathcal{F}}_2(\nabla_2)^{u; \lambda_2; \lambda_3} + 2(\tilde{\mathcal{F}}_3(\nabla_3)^{u; \lambda_2; \lambda_3} + \tilde{\mathcal{F}}_4(\nabla_4)^{u; \lambda_2; \lambda_3} + \tilde{\mathcal{F}}_5(\nabla_5)^{u; \lambda_2; \lambda_3} + \tilde{\mathcal{F}}_6(\nabla_6)^{u; \lambda_2; \lambda_3} \\
&+ \tilde{\mathcal{F}}_7(\nabla_7)^{u; \lambda_2; \lambda_3})]. \quad (3.26)
\end{aligned}$$

The functional form of the coefficients $(\nabla_i)^{u;\lambda_2;\lambda_3}\forall i$ after a basis transformation are explicitly mentioned in the Appendix. In the equilateral limit we have

$$[f_{\text{NL};2}^{\text{equil}}]^{u;(\lambda_2;\lambda_3)} = \frac{10\mathcal{Q}_u^{\text{POL}}}{9k^3} \frac{\left(\frac{3}{2} - v_T\right)^2 ((c_s + 2c_T)k)^{4v_T+2v_s-9} [\text{Cos}\left(\left[v_s - \frac{1}{2}\right]\frac{\pi}{2}\right)]^{\frac{1}{3}} [\text{Cos}\left(\left[v_T - \frac{1}{2}\right]\frac{\pi}{2}\right)]^{\frac{2}{3}}}{c_s^{2v_s-3} c_T^{4v_T-6} k^{v_s+2v_T}} \\ \times \left(2^{2v_s+4v_T-12} \left| \frac{\Gamma(v_s)}{\Gamma(\frac{3}{2})} \right|^2 \left| \frac{\Gamma(v_T)}{\Gamma(\frac{3}{2})} \right|^4 \frac{(1 - \epsilon_V - s_V^S)^2 (1 - \epsilon_V - s_V^T)^4 V^{\frac{3}{2}}(\phi)}{Y_S Y_T^2 c_T^4 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) [32\tilde{\mathcal{F}}_1(\nabla_1)_{\text{equil}}^{u;\lambda_2;\lambda_3} + 4\tilde{\mathcal{F}}_2(\nabla_2)_{\text{equil}}^{u;\lambda_2;\lambda_3} \\ + 2(\tilde{\mathcal{F}}_3(\nabla_3)_{\text{equil}}^{u;\lambda_2;\lambda_3} + \tilde{\mathcal{F}}_4(\nabla_4)_{\text{equil}}^{u;\lambda_2;\lambda_3} + \tilde{\mathcal{F}}_5(\nabla_5)_{\text{equil}}^{u;\lambda_2;\lambda_3} + \tilde{\mathcal{F}}_6(\nabla_6)_{\text{equil}}^{u;\lambda_2;\lambda_3} + \tilde{\mathcal{F}}_7(\nabla_7)_{\text{equil}}^{u;\lambda_2;\lambda_3})], \quad (3.27)$$

where each coefficients and functions are evaluated in equilateral limit.

3.3 Two-scalar one-tensor correlation

After gauge fixing the interactions involving one tensor and two scalars are given by the following third-order action:

$$S_{\zeta\zeta h} = \int dt d^3x a^3 \left\{ \frac{\mathcal{Y}_1}{a^2} h_{ij} \zeta_{,i} \zeta_{,j} + \frac{\mathcal{Y}_2}{a^2} \dot{h}_{ij} \zeta_{,i} \zeta_{,j} \right. \\ \left. + \mathcal{Y}_3 \dot{h}_{ij} \zeta_{,i} \psi_{,j} + \frac{\mathcal{Y}_4}{a^2} \partial^2 h_{ij} \zeta_{,i} \psi_{,j} + \frac{\mathcal{Y}_5}{a^4} \partial^2 h_{ij} \zeta_{,i} \zeta_{,j} \right. \\ \left. + \mathcal{Y}_6 \partial^2 h_{ij} \psi_{,i} \psi_{,j} \right\}, \quad (3.28)$$

where the dimensionful coefficients \mathcal{Y}_i ($i = 1, 2, \dots, 6$) are defined as

$$\mathcal{Y}_1 = Y_s c_s^2, \\ \mathcal{Y}_2 = \frac{L_1 \hat{K}_{XX}}{4} (Y_s c_s^2 - Y_T c_T^2) \\ + L_1 Y_T^2 \left[-\frac{1}{2} + \frac{H L_1 \hat{K}_{XX}}{4} \left(3 + \frac{\dot{Y}_T}{H Y_T} \right) \right. \\ \left. - \frac{1}{4} \frac{d}{dt} \left(L_1 \hat{K}_{XX} \right) \right] + \frac{\sigma Y_s c_s^2}{Y_T} + 2H L_1 Y_T \sigma \\ - Y_T \frac{d}{dt} (L_1 \sigma), \\ \mathcal{Y}_3 = Y_s \left[\frac{3}{2} + \frac{d}{dt} \left(\frac{\hat{K}_{XX} L_1}{2} + \frac{\sigma}{Y_T} \right) \right. \\ \left. - \left(3H + \frac{\dot{Y}_T}{Y_T} \right) \left(\frac{\hat{K}_{XX} L_1}{2} + \frac{\sigma}{Y_T} \right) \right],$$

$$\mathcal{Y}_4 = Y_s \left[-\frac{(Y_T - \hat{K}_{XX} c_T^2) L_1}{2} - 2H \sigma L_1 + \frac{d}{dt} (L_1 \sigma) \right. \\ \left. + \frac{\sigma}{Y_T^2} (Y_T c_T^2 - Y_s c_s^2) \right], \\ \mathcal{Y}_5 = \frac{Y_T^2 L_1}{2} \left[\frac{(Y_T - \hat{K}_{XX} c_T^2)}{2} + 2H L_1 \sigma \right. \\ \left. - \frac{d}{dt} (\sigma L_1) - \frac{\sigma}{Y_T^2} (3Y_T c_T^2 - Y_s c_s^2) \right], \\ \mathcal{Y}_6 = \frac{Y_s^2}{4Y_T} \left[1 + \frac{6H\sigma}{Y_T} - 2Y_T \frac{d}{dt} \left(\frac{\sigma}{Y_T^2} \right) \right]. \quad (3.29)$$

Following the prescription of the *in-in formalism* in the interaction picture *three-point two scalar one tensor correlation function* can be expressed in the following form:

$$\langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) h_{kl}(\vec{k}_3) \rangle = -i \sum_{q=1}^7 \int_{-\infty}^0 d\eta a \\ \times \langle 0 | [\zeta(\vec{k}_1) \zeta(\vec{k}_2) h_{kl}(\vec{k}_3), ([H_{\text{int}}^{(q)}(\eta)]_{kl})_{\zeta\zeta h}] | 0 \rangle \\ = (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) \{B_{\zeta\zeta h}\}_{kl}(\vec{k}_1, \vec{k}_2, \vec{k}_3), \quad (3.30)$$

where the total Hamiltonian can be expressed in terms of the third-order Lagrangian density as $([H_{\text{int}}(\eta)]_{kl})_{\zeta\zeta h} = \sum_{q=1}^7 ([H_{\text{int}}^{(q)}(\eta)]_{kl})_{\zeta\zeta h} = -\int d^3x [(\mathcal{L}_3)_{\zeta\zeta h}]_{kl}$. Here the cross bispectrum $\{B_{\zeta\zeta h}\}_{kl}$ is defined as

$$\{B_{\zeta\zeta h}\}_{kl} = \frac{(2\pi)^4 \mathcal{P}_u^2}{\prod_{i=1}^3 k_i^3} (\mathcal{A}_{\zeta\zeta h})_{kl} = \frac{6}{5} [f_{\text{NL};3}]_{kl}^u P_u^2, \quad (3.31)$$

where $(\mathcal{A}_{\zeta\zeta h})_{kl}$ is the two scalar one tensor correlation shape function and the symbol ; 3 represents two scalar one tensor correlation. Consequently the nonlinear parameter $[f_{\text{NL};3}]_{kl}^u$ can be expressed as

$$[f_{\text{NL};3}]_{kl}^u = \frac{10L_u^{\text{POL}} \mathcal{N}_{ij;kl} \underline{K}^{4v_s+2v_T-9} [\text{Cos}([v_s - \frac{1}{2}] \frac{\pi}{2})]^{\frac{2}{3}} [\text{Cos}([v_T - \frac{1}{2}] \frac{\pi}{2})]^{\frac{1}{3}}}{3 \sum_{i=1}^3 k_i^3 \frac{c_s^{4v_s-6} c_T^{2v_T-3} (k_1 k_2)^{v_s} k_3^{v_T}}{}} \times \left(2^{4v_s+2v_T-12} \left| \frac{\Gamma(v_s)}{\Gamma(\frac{3}{2})} \right|^4 \left| \frac{\Gamma(v_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{(1-\epsilon_V - s_V^S)^4 (1-\epsilon_V - s_V^T)^2 V^{\frac{3}{2}}(\phi)}{Y_S^2 Y_T c_s^6 c_T^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) \left(\sum_{v=1}^6 \mathcal{Y}_v(\hat{V}_v)_{ij} \right), \quad (3.32)$$

where the functional dependence of the coefficients $(\hat{V}_v)_{ij} \forall v$ are explicitly mentioned in Appendix B. In this context $\underline{K} := c_s(k_1 + k_2) + c_T k_3$.

For the quasi-exponential limit the overall normalization factor for the three types of polarization can be expressed as

$$\mathcal{L}_u^{\text{POL}} = \begin{cases} 1 & : u = 1 \text{ (E - mode)} \\ 16 & : u = 2 \text{ (E} \otimes \text{B mode)} \\ 256 & : u = 3 \text{ (B - mode)}. \end{cases} \quad (3.33)$$

As mentioned in the previous subsection, performing a basis transformation cross bispectrum for two scalars and one tensor can be expressed as

$$\langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \bigoplus_{\lambda}^{\lambda} \zeta(\vec{k}_3) \rangle = (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) B_{\lambda}^{(\zeta\zeta h)}(\vec{k}_1, \vec{k}_2, \vec{k}_3). \quad (3.34)$$

where we have used the following parameterization:

$$B_{\lambda}^{(\zeta\zeta h)} = \frac{(2\pi)^4 \mathcal{P}_u^2}{\prod_{i=1}^3 k_i^3} \mathcal{A}_{(\zeta\zeta h)}^{\lambda} = \frac{6}{5} [f_{\text{NL};3}]^{u;\lambda} P_u^2. \quad (3.35)$$

The polarized non-Gaussian parameter for two scalar and one tensor mode $[f_{\text{NL};3}]^{u;\lambda}$ can be rewritten as

$$[f_{\text{NL};3}]_{\lambda}^{\text{equil}} = \frac{20L_u^{\text{POL}} \delta_{\lambda\lambda'}}{9k^3} \frac{((2c_s + c_T)k)^{4v_s+2v_T-9} [\text{Cos}([v_s - \frac{1}{2}] \frac{\pi}{2})]^{\frac{2}{3}} [\text{Cos}([v_T - \frac{1}{2}] \frac{\pi}{2})]^{\frac{1}{3}}}{c_s^{4v_s-6} c_T^{2v_T-3} k^{2v_s+v_T}} \times \left(2^{4v_s+2v_T-12} \left| \frac{\Gamma(v_s)}{\Gamma(\frac{3}{2})} \right|^4 \left| \frac{\Gamma(v_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{(1-\epsilon_V - s_V^S)^4 (1-\epsilon_V - s_V^T)^2 V^{\frac{3}{2}}(\phi)}{Y_S^2 Y_T c_s^6 c_T^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) \left(\sum_{v=1}^6 \mathcal{Y}_v(\hat{V}_v)_{\lambda'}^{\text{equil}} \right). \quad (3.37)$$

3.4 Three-tensor correlation

The interactions involving three tensors are given by the following third-order action:

$$S_{hhh} = \int dt d^3x a^3 \left\{ \frac{\sigma}{12} \dot{h}_{ij} \dot{h}_{jk} \dot{h}_{ki} + \frac{Y_T}{4a^2 c_T^2} \times \left(h_{ik} h_{jl} - \frac{1}{2} h_{ij} h_{kl} \right) h_{ij,kl} \right\}. \quad (3.38)$$

$$[f_{\text{NL};3}]_{\lambda}^u = \frac{20L_u^{\text{POL}} \delta_{\lambda\lambda'} \underline{K}^{4v_s+2v_T-9} [\text{Cos}([v_s - \frac{1}{2}] \frac{\pi}{2})]^{\frac{2}{3}} [\text{Cos}([v_T - \frac{1}{2}] \frac{\pi}{2})]^{\frac{1}{3}}}{3 \sum_{i=1}^3 k_i^3 \frac{c_s^{4v_s-6} c_T^{2v_T-3} (k_1 k_2)^{v_s} k_3^{v_T}}{}} \times \left(2^{4v_s+2v_T-12} \left| \frac{\Gamma(v_s)}{\Gamma(\frac{3}{2})} \right|^4 \left| \frac{\Gamma(v_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{(1-\epsilon_V - s_V^S)^4 (1-\epsilon_V - s_V^T)^2 V^{\frac{3}{2}}(\phi)}{Y_S^2 Y_T c_s^6 c_T^3 \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) \left(\sum_{v=1}^6 \mathcal{Y}_v(\hat{V}_v)_{\lambda'} \right), \quad (3.36)$$

where all the coefficients $(\hat{V}_v)_{\lambda'} \forall v$ after a basis transformation are explicitly written in Appendix B.

In the equilateral limit the expression for the non-Gaussian parameter (f_{NL}) reduces to the following form:

Now following the prescription of the *in-in formalism* in the interaction picture the *three-point three-tensor correlation function* can be expressed in the following form:

$$\begin{aligned}
 & \langle h_{i_1 j_1}(\vec{k}_1) h_{i_2 j_2}(\vec{k}_2) h_{i_3 j_3}(\vec{k}_3) \rangle \\
 &= -i \int_{-\infty}^0 d\eta a \langle [h_{i_1 j_1}(\vec{k}_1) h_{i_2 j_2}(\vec{k}_2) h_{i_3 j_3}(\vec{k}_3), \\
 &\quad \times ([H_{\text{int}}(\eta)]_{i_1 j_1 i_2 j_2 i_3 j_3})_{hhh}] | 0 \rangle \\
 &= (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) \{B_{hhh}\}_{i_1 j_1 i_2 j_2 i_3 j_3}(\vec{k}_1, \vec{k}_2, \vec{k}_3),
 \end{aligned} \quad (3.39)$$

where the total Hamiltonian is expressed in terms of the third-order Lagrangian density as $([H_{\text{int}}(\eta)]_{i_1 j_1 i_2 j_2 i_3 j_3})_{hhh} = -\int d^3x [(\mathcal{L}_3)_{hhh}]_{i_1 j_1 i_2 j_2 i_3 j_3}$. In this context the bispectrum for the three-tensor correlation can be expressed as

$$\begin{aligned}
 \{B_{hhh}\}_{i_1 j_1 i_2 j_2 i_3 j_3}(\vec{k}_1, \vec{k}_2, \vec{k}_3) &= \frac{(2\pi)^4 \mathcal{P}_u^2}{\prod_{i=1}^3 k_i^3} \mathcal{A}_{i_1 j_1 i_2 j_2 i_3 j_3}^{hhh} \\
 &= \frac{6}{5} [f_{\text{NL};4}] P_u^2,
 \end{aligned} \quad (3.40)$$

where the symbol ; 4 represents three-tensor correlation. Also, the non-Gaussian parameter is given by

$$\begin{aligned}
 [f_{\text{NL};4}]_{i_1 j_1 i_2 j_2 i_3 j_3} &= \frac{10 \mathcal{W}_u^{\text{POL}} K^{9-6\nu_T} \text{Cos}\left(\left[\nu_T - \frac{1}{2}\right] \frac{\pi}{2}\right)}{3 \sum_{i=1}^3 k_i^3 (k_1 k_2 k_3)^{2\nu_T}} \\
 &\times \left(2^{3(\nu_s + \nu_T) - 11} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^3 \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^3 \right. \\
 &\times \left. \frac{(1 - \epsilon_V - s_V^S)^3 (1 - \epsilon_V - s_V^T)^3 V^{\frac{3}{2}}(\phi)}{Y_S^{\frac{3}{2}} Y_T^{\frac{3}{2}} c_s^{\frac{9}{2}} c_T^{\frac{9}{2}} \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) \\
 &\times \left(\sum_{p=1}^3 \Delta_{i_1 j_1 i_2 j_2 i_3 j_3}^{(p)} \right),
 \end{aligned} \quad (3.41)$$

where $K = k_1 + k_2 + k_3$ and the polarization index $u = 1(\text{E-mode}), 2(\text{E} \otimes \text{B-mode}), 3(\text{B-mode})$. The functional dependence of all the coefficients $\Delta_{i_1 j_1 i_2 j_2 i_3 j_3}^{(p)} \forall p$ are summarized in Appendix B. For the quasi-exponential limit the overall normalization factor for the three types of polarization can be expressed as

$$\mathcal{W}_u^{\text{POL}} = \begin{cases} 4 & : u = 1 (\text{E-mode}) \\ 64 & : u = 2 (\text{E} \otimes \text{Bmode}) \\ 1024 & : u = 3 (\text{B-mode}). \end{cases} \quad (3.42)$$

After performing a basis transformation the relevant three-point correlation function for the three-tensor interaction can be expressed in terms of the bispectrum as

$$\begin{aligned}
 & \left\langle \bigoplus^{\lambda_1}(\vec{k}_1) \bigoplus^{\lambda_2}(\vec{k}_2) \bigoplus^{\lambda_3}(\vec{k}_3) \right\rangle \\
 &= (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3) B_{\lambda_1, \lambda_2, \lambda_3}^{hhh}.
 \end{aligned} \quad (3.43)$$

where

$$B_{\lambda_1, \lambda_2, \lambda_3}^{hhh} = \frac{(2\pi)^4 \mathcal{P}_u^2}{\prod_{i=1}^3 k_i^3} \mathcal{A}_{(\zeta \zeta h)}^{\lambda_1, \lambda_2, \lambda_3} = \frac{6}{5} [f_{\text{NL};4}]_{\lambda_1, \lambda_2, \lambda_3}^u P_u^2, \quad (3.44)$$

where the nonlinear parameter is given by

$$\begin{aligned}
 [f_{\text{NL};4}]_{\lambda_1, \lambda_2, \lambda_3}^u &= \frac{10 \mathcal{W}_u^{\text{POL}} K^{9-6\nu_T} \text{Cos}\left(\left[\nu_T - \frac{1}{2}\right] \frac{\pi}{2}\right)}{3 \sum_{i=1}^3 k_i^3 (k_1 k_2 k_3)^{2\nu_T}} \\
 &\times \left(2^{3(\nu_s + \nu_T) - 11} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^3 \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^3 \right. \\
 &\times \left. \frac{(1 - \epsilon_V - s_V^S)^3 (1 - \epsilon_V - s_V^T)^3 V^{\frac{3}{2}}(\phi)}{Y_S^{\frac{3}{2}} Y_T^{\frac{3}{2}} c_s^{\frac{9}{2}} c_T^{\frac{9}{2}} \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) \\
 &\times \left(\sum_{p=1}^3 \Delta_{\lambda_1 \lambda_2 \lambda_3}^{(p)} \right).
 \end{aligned} \quad (3.45)$$

Once again, all the helicity dependent coefficients $\Delta_{\lambda_1 \lambda_2 \lambda_3}^{(p)} \forall p$ after a basis transformation are explicitly mentioned in Appendix B.

In the equilateral limit we have

$$\begin{aligned}
 [f_{\text{NL};4}]_{\lambda_1, \lambda_2, \lambda_3}^{\text{equil}} &= \frac{10 \mathcal{W}_u^{\text{POL}} (3k)^{9-6\nu_T} \text{Cos}\left(\left[\nu_T - \frac{1}{2}\right] \frac{\pi}{2}\right)}{9k^3 k^{6\nu_T}} \\
 &\times \left(2^{3(\nu_s + \nu_T) - 11} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^3 \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^3 \right. \\
 &\times \left. \frac{(1 - \epsilon_V - s_V^S)^3 (1 - \epsilon_V - s_V^T)^3 V^{\frac{3}{2}}(\phi)}{Y_S^{\frac{3}{2}} Y_T^{\frac{3}{2}} c_s^{\frac{9}{2}} c_T^{\frac{9}{2}} \tilde{g}_1^{\frac{3}{2}} M_{\text{PL}}^3} \right) \\
 &\times \left(\sum_{p=1}^3 \Delta_{\lambda_1 \lambda_2 \lambda_3}^{(p); \text{equil}} \right).
 \end{aligned} \quad (3.46)$$

The numerical values of all such non-Gaussian parameters from three-point correlation for different polarizing modes are mentioned in the Table 1. In this context **PC** and **PV** stands for the parity conserving and violating contribution for the graviton degrees of freedom.

4 Tree level trispectrum analysis from four-scalar correlation

To derive the expression for scalar trispectrum for D3 DBI Galileon let us start from fourth-order action up to total derivatives. Consequently the fourth-order action in the uni-form gauge can be expressed as

$$S_{\zeta \zeta \zeta \zeta} = S_{\text{CI}} + S_{\text{SE}} + S_{\text{GE}}, \quad (4.1)$$

where S_{CI} , S_{SE} , and S_{GE} represent the contribution from the *contact interaction*, *scalar exchange* and *graviton exchange* appearing in the four-point correlator. In the next subsections we will discuss the individual contributions separately.

Table 1 Different non-Gaussian ($[f_{\text{NL};A}]^{u;(\lambda_1\lambda_2\lambda_3)}$) parameters related to the primordial bispectrum for $A = 1$ (three scalar), 2 (one scalar and two tensor), 3 (two scalar and one tensor), 4 (three tensor) with polarization index $u = 1$ (E – mode), 2 (E \otimes B – mode), 3 (B – mode) including all helicity degrees of freedom represented by λ_1, λ_2 , and λ_3 esti-

mated from our model. In this context “+” and “–” stand for the two projections of helicity for the graviton degrees of freedom and “0” represents the helicity for the scalar mode. Here **PC** and **PV** stand for the parity conserving and violating contributions appearing in the tree level primordial bispectrum analysis

$[f_{\text{NL};A}]^{u;(\lambda_1\lambda_2\lambda_3)}$ (E-mode)	$\times 10^{-3}$	$[f_{\text{NL};A}]^{u;(\lambda_1\lambda_2\lambda_3)}$ (E \otimes B-mode)	$\times 10^{-3}$	$[f_{\text{NL};A}]^{u;(\lambda_1\lambda_2\lambda_3)}$ (B-mode)	$\times 10^{-4}$
$[f_{\text{NL};1}]^{1;(000)}$ (PC)	4000–7000	$[f_{\text{NL};1}]^{2;(000)}$ (PC)	0	$[f_{\text{NL};1}]^{3;(000)}$ (PC)	0
$[f_{\text{NL};2}]^{1;(0++)}$ (PV)	3.2–6.7	$[f_{\text{NL};2}]^{2;(0++)}$ (PV)	2.1–4.5	$[f_{\text{NL};2}]^{3;(0++)}$ (PV)	2.8–8.7
$[f_{\text{NL};2}]^{1;(0--)}$ (PV)	1.4–5.7	$[f_{\text{NL};2}]^{2;(0--)}$ (PV)	2.1–8.9	$[f_{\text{NL};2}]^{3;(0--)}$ (PV)	2.7–7.2
$[f_{\text{NL};2}]^{1;(0+-)}$ (PV)	2.6–9.6	$[f_{\text{NL};2}]^{2;(0+-)}$ (PV)	2.9–11.0	$[f_{\text{NL};2}]^{3;(0+-)}$ (PV)	2.7–8.4
$[f_{\text{NL};2}]^{1;(0-+)}$ (PV)	1.7–6.9	$[f_{\text{NL};2}]^{2;(0-+)}$ (PV)	3.5–7.4	$[f_{\text{NL};2}]^{3;(0-+)}$ (PV)	1.8–10.6
$[f_{\text{NL};3}]^{1;(00+)}$ (PC)	121–432	$[f_{\text{NL};3}]^{2;(00+)}$ (PC)	78–349	$[f_{\text{NL};3}]^{3;(00+)}$ (PC)	45–221
$[f_{\text{NL};3}]^{1;(00-)}$ (PC)	549–878	$[f_{\text{NL};3}]^{2;(00-)}$ (PC)	304–883	$[f_{\text{NL};3}]^{3;(00-)}$ (PC)	189–588
$[f_{\text{NL};4}]^{1;(++++)}$ (PV)	0.23–0.97	$[f_{\text{NL};4}]^{2;(++++)}$ (PV)	0.08–0.32	$[f_{\text{NL};4}]^{3;(++++)}$ (PV)	0.02–0.34
$[f_{\text{NL};4}]^{1;(-- --)}$ (PV)	0.06–0.41	$[f_{\text{NL};4}]^{2;(-- --)}$ (PV)	0.09–0.67	$[f_{\text{NL};4}]^{3;(-- --)}$ (PV)	0.23–1.7
$[f_{\text{NL};4}]^{1;(+ + -)}$ (PV)	0.23–0.93	$[f_{\text{NL};4}]^{2;(+ + -)}$ (PV)	0.18–0.67	$[f_{\text{NL};4}]^{3;(+ + -)}$ (PV)	0.03–0.53
$[f_{\text{NL};4}]^{1;(+ - -)}$ (PV)	0.01–0.35	$[f_{\text{NL};4}]^{2;(+ - -)}$ (PV)	0.07–0.44	$[f_{\text{NL};4}]^{3;(+ - -)}$ (PV)	0.02–0.42
$[f_{\text{NL};4}]^{1;(- + -)}$ (PV)	0.04–0.39	$[f_{\text{NL};4}]^{2;(- + -)}$ (PV)	0.02–0.32	$[f_{\text{NL};4}]^{3;(- + -)}$ (PV)	0.09–0.51
$[f_{\text{NL};4}]^{1;(- + +)}$ (PV)	0.03–0.56	$[f_{\text{NL};4}]^{2;(- + +)}$ (PV)	0.1–0.43	$[f_{\text{NL};4}]^{3;(- + +)}$ (PV)	0.17–0.63
$[f_{\text{NL};4}]^{1;(- - +)}$ (PV)	0.09–0.34	$[f_{\text{NL};4}]^{2;(- - +)}$ (PV)	0.07–0.41	$[f_{\text{NL};4}]^{3;(- - +)}$ (PV)	0.05–0.44

4.1 Contact interaction

Taking into account the contribution coming from contact interaction of effective DBI Galileon in the fourth-order action in uniform gauge we get

$$S_{\text{CI}} = \int dt d^3x \frac{a^3}{4} \left\{ \bar{\mathcal{U}}_1 \dot{\zeta}^4 - \frac{(\partial \zeta)^2}{a^2} \dot{\zeta}^2 \bar{\mathcal{U}}_2 + \bar{\mathcal{U}}_3 \frac{(\partial \zeta)^4}{a^4} \right\}, \quad (4.2)$$

where the coefficients $\bar{\mathcal{U}}_i$ ($i = 1, 2, 3$) for the effective DBI Galileon are defined as

$$\begin{aligned} \bar{\mathcal{U}}_1 &= \left(\frac{\dot{\phi}^4}{6} [\hat{K}_{4X} - \tilde{G}_{4X} \dot{\phi}^2] + \dot{\phi}^2 [\hat{K}_{XX} - \tilde{G}_{XX} \dot{\phi}^2] \right. \\ &\quad \left. + \frac{1}{2} [\hat{K}_{XX} - \tilde{G}_{XX} \dot{\phi}^2] \right), \\ \bar{\mathcal{U}}_2 &= (\dot{\phi}^2 [\hat{K}_{XX} - \tilde{G}_{XX} \dot{\phi}^2] + \hat{K}_{XX} - \tilde{G}_{XX} \dot{\phi}^2), \\ \bar{\mathcal{U}}_3 &= \frac{1}{2} [\hat{K}_{XX} - \tilde{G}_{XX} \dot{\phi}^2], \end{aligned} \quad (4.3)$$

where $\hat{K}(\phi, X)$ and $\tilde{G}(\phi, X)$ are explicitly mentioned in Eq. (2.5). Using the in-in procedure the *four-point correlator function* for quasi-exponential situation can be expressed in the following form:

$$\begin{aligned} \langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4) \rangle^{\text{CI}} &= -i \sum_{j=1}^3 \int_{-\infty}^0 d\eta a \\ &\quad \times \langle 0 | [\zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4), (H_{\text{int}}^{(j)}(\eta))^{\text{CI}}_{\zeta\zeta\zeta\zeta}] | 0 \rangle \\ &= (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) \mathcal{T}_{\zeta}^{\text{CI}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4), \end{aligned} \quad (4.4)$$

where in the interaction picture the Hamiltonian can be written as $(H_{\text{int}}(\eta))^{\text{CI}}_{\zeta\zeta\zeta\zeta} = \sum_{j=1}^3 (H_{\text{int}}^{(j)}(\eta))^{\text{CI}}_{\zeta\zeta\zeta\zeta}$.

Here following the ansatz used in [22] the *trispectrum* $\mathcal{T}_{\zeta}^{\text{CI}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4)$ for contact interaction is defined as

$$\begin{aligned} \mathcal{T}_{\zeta}^{\text{CI}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4) &= \frac{1}{\prod_{i=1}^4 k_i^3} \\ &\quad \times [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) \\ &\quad + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] \{ \tau_{\text{NL}}^{\text{CI}} P_{\zeta(1)}^3 + \frac{54}{25} s_{\text{NL}}^{\text{CI}} P_{\zeta(2)}^3 \}, \end{aligned} \quad (4.5)$$

where

$$\begin{aligned} P_{\zeta(1)}^3 &= \sum_{j < p, i \neq j, p} P_{\zeta}(k_{ij}) P_{\zeta}(k_j) P_{\zeta}(k_p), \\ P_{\zeta(2)}^3 &= \sum_{i < j < p} P_{\zeta}(k_i) P_{\zeta}(k_j) P_{\zeta}(k_p), \end{aligned} \quad (4.6)$$

such that

$$P_{\zeta}^3 = P_{\zeta(1)}^3 + \frac{3456}{25} \frac{1}{\bar{K}^3} [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] P_{\zeta(2)}^3, \quad (4.7)$$

and $\tau_{\text{NL}}^{\text{CI}}$ and $g_{\text{NL}}^{\text{CI}}$ are the two nonlinear parameters which carry the signatures of primordial non-Gaussianities of the curvature perturbation in the trispectrum analysis. By knowing $\tau_{\text{NL}}^{\text{CI}}$ the other parameter $g_{\text{NL}}^{\text{CI}}$ can be calculated by making use of the following relation [65]:

$$g_{\text{NL}}^{\text{CI}} = \frac{64}{\bar{K}^3} [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] \tau_{\text{NL}}^{\text{CI}}, \quad (4.8)$$

where $\bar{K} = k_1 + k_2 + k_3 + k_4$. Therefore, there is only one independent piece of information, namely $\tau_{\text{NL}}^{\text{CI}}$, which carries information as regards the trispectrum obtained from the *contact interaction*.

To proceed, we denote the angle between \vec{k}_i and \vec{k}_j (with $i \neq j$) by Θ_{ij} ; then

$$\begin{aligned} \cos(\Theta_{12}) &= \cos(\Theta_{34}) := \cos(\Theta_3), \\ \cos(\Theta_{23}) &= \cos(\Theta_{14}) := \cos(\Theta_1), \\ \cos(\Theta_{13}) &= \cos(\Theta_{24}) := \cos(\Theta_2) \end{aligned} \quad (4.9)$$

subject to the constraint

$\cos(\Theta_1) + \cos(\Theta_2) + \cos(\Theta_3) = -1$ comes from the conservation of momentum. Additionally we have used

$$\begin{aligned} k_{14} &= k_{23} = |\vec{k}_1 + \vec{k}_4| = |\vec{k}_2 + \vec{k}_3| \\ &= \sqrt{k_1^2 + k_4^2 + 2k_1 k_4 \cos(\Theta_1)} \\ &= \sqrt{k_2^2 + k_3^2 + 2k_2 k_3 \cos(\Theta_1)}, \\ k_{24} &= k_{13} = |\vec{k}_2 + \vec{k}_4| = |\vec{k}_1 + \vec{k}_3| \\ &= \sqrt{k_2^2 + k_4^2 + 2k_2 k_4 \cos(\Theta_2)} \\ &= \sqrt{k_1^2 + k_3^2 + 2k_1 k_3 \cos(\Theta_2)}, \\ k_{34} &= k_{12} = |\vec{k}_3 + \vec{k}_4| = |\vec{k}_1 + \vec{k}_2| \\ &= \sqrt{k_3^2 + k_4^2 + 2k_3 k_4 \cos(\Theta_3)} \\ &= \sqrt{k_1^2 + k_2^2 + 2k_1 k_2 \cos(\Theta_3)}. \end{aligned} \quad (4.10)$$

The explicit form of $\tau_{\text{NL}}^{\text{CI}}$ characterizing the trispectrum obtained from the *contact interaction* can be expressed for our model as

$$\begin{aligned} \tau_{\text{NL}}^{\text{CI}} &= \frac{2^{8\nu_s-6} \pi^6 \cos\left(\left[\nu_s - \frac{1}{2}\right] \frac{\pi}{2}\right)}{[(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})]} \\ &\times \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \frac{(1 - \epsilon_V - s_V^S)^8 H^8}{Y_S^4 c_s^{12} (k_1 k_2 k_3 k_4)^{2\nu_s}} \left\{ \frac{8\bar{\mathcal{U}}_1 \bar{K}^{8\nu_s-5}}{13} [\Gamma(17 - 8\nu_s) \right. \\ &\times \bar{K}^8 G_1 - i\Gamma(16 - 8\nu_s) \bar{K}^7 G_2 \\ &+ \Gamma(15 - 8\nu_s) \bar{K}^6 G_3 - i\Gamma(14 - 8\nu_s) \bar{K}^5 G_4 \\ &+ \Gamma(13 - 8\nu_s) \bar{K}^4 G_5 - i\Gamma(12 - 8\nu_s) \bar{K}^3 G_6 \\ &+ \Gamma(11 - 8\nu_s) \bar{K}^2 G_7 - i\Gamma(10 - 8\nu_s) \bar{K} G_8 + G_9] \\ &+ \frac{\bar{\mathcal{U}}_2 \bar{K}^{8\nu_s-3}}{32} [(\vec{k}_3, \vec{k}_4) \bar{\mathcal{I}}(3, 4; 1, 2) + (\vec{k}_2, \vec{k}_4) \bar{\mathcal{I}}(2, 4; 1, 3) \\ &+ (\vec{k}_2, \vec{k}_3) \bar{\mathcal{I}}(2, 3; 1, 4) + (\vec{k}_1, \vec{k}_4) \bar{\mathcal{I}}(1, 4; 2, 3) \\ &+ (\vec{k}_1, \vec{k}_2) \bar{\mathcal{I}}(1, 2; 3, 4) + (\vec{k}_1, \vec{k}_3) \bar{\mathcal{I}}(1, 3; 2, 4)] \\ &+ \frac{\bar{\mathcal{U}}_3 \bar{K}^{8\nu_s+12}}{8} [(\vec{k}_1, \vec{k}_2)(\vec{k}_3, \vec{k}_4) + (\vec{k}_1, \vec{k}_3)(\vec{k}_2, \vec{k}_4) \\ &+ (\vec{k}_1, \vec{k}_4)(\vec{k}_2, \vec{k}_3)] \left(\frac{\bar{\mathcal{Z}}_1 \Gamma(13 - 8\nu_s)}{(\bar{K})^{13}} + \frac{\bar{\mathcal{Z}}_2 \Gamma(14 - 8\nu_s)}{(\bar{K})^{14}} \right. \\ &\left. - \frac{\bar{\mathcal{Z}}_3 \Gamma(15 - 8\nu_s)}{(\bar{K})^{15}} - \frac{\bar{\mathcal{Z}}_4 \Gamma(16 - 8\nu_s)}{(\bar{K})^{16}} + \frac{\bar{\mathcal{Z}}_5 \Gamma(17 - 8\nu_s)}{(\bar{K})^{17}} \right) \Big\} \end{aligned} \quad (4.11)$$

where the functional dependence of the momentum dependent functions $G_i \forall i$, $\mathcal{Z}_q \forall q$ and $\bar{\mathcal{I}}(i, j; m, n)$ are given in Appendix B. It is important to mention here that the 4D effective coupling and the interaction between the higher order graviton and the DBI Galileon plays a significant role in the slow-roll regime. From Eq. (4.11) it is evident that the non-Gaussian parameter $\tau_{\text{NL}}^{\text{CI}}$ obtained from the contact interaction is inversely proportional to the 12th power of the sound speed for the scalar mode. But depending on the signature and strength of the Gauss–Bonnet coupling the behavior of the $\tau_{\text{NL}}^{\text{CI}}$ changes.

Further, using the *equilateral configuration* ($k_1 = k_2 = k_3 = k_4 = k$ and $\bar{K} = 4k$) and incorporating the contribution from the maximum shape of the trispectrum ($\cos(\Theta_1) = \cos(\Theta_2) = \cos(\Theta_3) = -\frac{1}{3}$ and k_{ij} (for $i < j$) = $\frac{2k}{\sqrt{3}}$) the nonlinear parameter can be expressed as

$$\begin{aligned} \tau_{\text{NL}}^{\text{equil; CI}} &= \frac{2^{24\nu_s-5} \pi^6 \cos\left(\left[\nu_s - \frac{1}{2}\right] \frac{\pi}{2}\right)}{9\sqrt{3}k^3} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \\ &\times \frac{(1 - \epsilon_V - s_V^S)^8 H^8}{Y_S^4 c_s^{12}} \left\{ \frac{8\bar{\mathcal{U}}_1}{13312k^5} [65536\Gamma(17 - 8\nu_s)k^8 G_1^{\text{equil}} \right. \\ &- 16384i\Gamma(16 - 8\nu_s)k^7 G_2^{\text{equil}} + 4096\Gamma(15 - 8\nu_s)k^6 G_3^{\text{equil}} \\ &- 1024i\Gamma(14 - 8\nu_s)k^5 G_4^{\text{equil}} \\ &+ 256\Gamma(13 - 8\nu_s)k^4 G_5^{\text{equil}} - 64i\Gamma(12 - 8\nu_s)k^3 G_6^{\text{equil}} \\ &+ 16\Gamma(11 - 8\nu_s)k^2 G_7^{\text{equil}} \\ &\left. - 4i\Gamma(10 - 8\nu_s)k G_8^{\text{equil}} + G_9^{\text{equil}}] - \frac{\bar{\mathcal{U}}_2}{1024k} \bar{\mathcal{I}}^{\text{equil}} \right\} \end{aligned}$$

$$\begin{aligned}
& + \frac{838861\bar{U}_3}{12} \left(\frac{\bar{Z}_1^{\text{equil}} k^3 \Gamma(13 - 8\nu_s)}{67108864} \right. \\
& + \frac{\bar{Z}_2^{\text{equil}} k^2 \Gamma(14 - 8\nu_s)}{268435456} - \frac{\bar{Z}_3^{\text{equil}} k \Gamma(15 - 8\nu_s)}{1073741824} \\
& \left. - \frac{\bar{Z}_4^{\text{equil}} \Gamma(16 - 8\nu_s)}{4294967296} + \frac{\bar{Z}_5^{\text{equil}} \Gamma(17 - 8\nu_s)}{17179869184} \right). \quad (4.12)
\end{aligned}$$

4.2 Scalar exchange

Within the in-in picture formalism, to calculate the four-point correlation function resulting from a correlation established via the scalar exchange mode of effective DBI Galileon we start with the following action in the uniform gauge:

$$S_{\text{SE}} = \int dt d^3x a^3 \left\{ \mathbf{A} \dot{\zeta}^3 - \frac{(\partial \zeta)^2}{a^2} \dot{\zeta} \cdot \mathbf{B} \right\}, \quad (4.13)$$

where the coefficients (\mathbf{A} , \mathbf{B}) are defined as

$$\begin{aligned}
\mathbf{A} &= \left(\frac{\dot{\phi}}{2} [\hat{K}_{XX} - \tilde{G}_{XX}] + \frac{\dot{\phi}^3}{6} [\hat{K}_{XXX} - \tilde{G}_{XXX} \dot{\phi}^2] \right), \\
\mathbf{B} &= -\frac{\dot{\phi}}{2} [\hat{K}_{XX} - \tilde{G}_{XX} \dot{\phi}^2].
\end{aligned} \quad (4.14)$$

Using the in-in procedure the *four-point correlator function* for the quasi-exponential limit can be expressed in the following form:

$$\begin{aligned}
\langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4) \rangle^{\text{SE}} &= -i \sum_{j=1}^2 \sum_{p=1}^2 \int_{-\infty}^0 d\eta \int_{-\infty}^{\eta} d\tilde{\eta} \\
&\times \langle 0 | [\zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4), (H_{\text{int}}^{(j)}(\eta))^{\text{SE}}_{\zeta\zeta\zeta}, (H_{\text{int}}^{(p)}(\tilde{\eta}))^{\text{SE}}_{\zeta\zeta\zeta}] | 0 \rangle \\
&= (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) \mathcal{T}_{\zeta}^{\text{SE}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4), \quad (4.15)
\end{aligned}$$

where in the interaction picture the Hamiltonian can be written in terms of the third-order Lagrangian density as $(H_{\text{int}}(\eta))^{\text{SE}}_{\zeta\zeta\zeta} = \sum_{j=1}^2 (H_{\text{int}}^{(j)}(\eta))^{\text{SE}}_{\zeta\zeta\zeta} = -\int d^3x \mathcal{L}_3^{\text{SE}}$. Hence following the ansatz used in [22] the *trispectrum* $\mathcal{T}_{\zeta}^{\text{SE}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4)$ is defined as

$$\begin{aligned}
\mathcal{T}_{\zeta}^{\text{SE}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4) &= \frac{1}{\prod_{i=1}^4 k_i^3} [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) \\
&\quad + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) \\
&\quad + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] \\
&\quad \times \left\{ \tau_{\text{NL}}^{\text{SE}} P_{\zeta(1)}^3 + \frac{54}{25} g_{\text{NL}}^{\text{SE}} P_{\zeta(2)}^3 \right\}, \quad (4.16)
\end{aligned}$$

where $\tau_{\text{NL}}^{\text{SE}}$ and $g_{\text{NL}}^{\text{SE}}$ are the two nonlinear parameters which carry the signatures of primordial non-Gaussianities of the curvature perturbation obtained from the scalar exchange contribution in the trispectrum analysis. By knowing $\tau_{\text{NL}}^{\text{SE}}$ the other parameter, $g_{\text{NL}}^{\text{SE}}$, can be calculated by making use of the following relation [65]:

$$\begin{aligned}
g_{\text{NL}}^{\text{SE}} &= \frac{64}{\bar{K}^3} [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3) \\
&\quad \times (k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] \tau_{\text{NL}}^{\text{SE}}, \quad (4.17)
\end{aligned}$$

where $\bar{K} = k_1 + k_2 + k_3 + k_4$. The explicit form of $\tau_{\text{NL}}^{\text{SE}}$ characterizing the *scalar exchange* trispectrum can be expressed for our model as:

$$\begin{aligned}
\tau_{\text{NL}}^{\text{SE}} &= \frac{2^{8\nu_s-14} \bar{K}^{10\nu_s-15} \text{Cos}\left(\left[\nu_s - \frac{1}{2}\right] \frac{\pi}{2}\right)}{[(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})]} \\
&\times \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \frac{(1 - \epsilon_V - s_V^S)^8 H^8}{Y_S^5 c_S^6 (k_1 k_2 k_3 k_4)^{2\nu_s}} \{ 9\mathbf{A}^2 [\Xi_1(-k_1, -k_2, -k_{12}, k_3, k_4, k_{12}) - \Xi_1(k_1, k_2, -k_{12}, k_3, k_4, k_{12})] \\
&\quad + \mathbf{AB} [3(\vec{k}_3, \vec{k}_4) \{ \Xi_3(k_1, k_2, -k_{12}, k_{12}, k_3, k_4) - \Xi_3(-k_1, -k_2, -k_{12}, k_{12}, k_3, k_4) \} \\
&\quad + 6(\vec{k}_{12}, \vec{k}_4) \{ \Xi_3(k_1, k_2, -k_{12}, k_3, k_4, k_{12}) - \Xi_3(-k_1, -k_2, -k_{12}, k_3, k_4, k_{12}) \} \\
&\quad + 3(\vec{k}_1, \vec{k}_2) \{ \Xi_4(-k_{12}, k_1, k_2, k_3, k_4, k_{12}) - \Xi_4(-k_{12}, -k_1, -k_2, k_3, k_4, k_{12}) \} \\
&\quad - 6(\vec{k}_{12}, \vec{k}_2) \{ \Xi_4(k_1, k_2, -k_{12}, k_3, k_4, k_{12}) - \Xi_4(-k_1, -k_2, -k_{12}, k_3, k_4, k_{12}) \}] \\
&\quad - \mathbf{B}^2 [(\vec{k}_1, \vec{k}_2)(\vec{k}_3, \vec{k}_4) \{ \Xi_2(-k_{12}, k_1, k_2, k_{12}, k_3, k_4) - \Xi_2(-k_{12}, -k_1, -k_2, k_{12}, k_3, k_4) \} \\
&\quad + 2(\vec{k}_1, \vec{k}_2)(\vec{k}_{12}, \vec{k}_4) \{ \Xi_2(-k_{12}, k_1, k_2, k_3, k_4, k_{12}) - \Xi_2(-k_{12}, -k_1, -k_2, k_3, k_4, k_{12}) \} \\
&\quad - 2(\vec{k}_3, \vec{k}_4)(\vec{k}_{12}, \vec{k}_2) \{ \Xi_2(k_1, k_2, -k_{12}, k_{12}, k_3, k_4) - \Xi_2(-k_1, -k_2, -k_{12}, k_{12}, k_3, k_4) \} \\
&\quad - 4(\vec{k}_{12}, \vec{k}_4)(\vec{k}_{12}, \vec{k}_2) \{ \Xi_2(k_1, k_2, -k_{12}, k_3, k_4, k_{12}) - \Xi_2(-k_1, -k_2, -k_{12}, k_3, k_4, k_{12}) \}] \\
&\quad + 23 \text{ permutations of } (k_1, k_2, k_3, k_4) \}, \quad (4.18)
\end{aligned}$$

where the momentum dependent functions $\Xi_i \forall i$ are mentioned in the Appendix. Further, using the *equilateral configuration* the non-Gaussian parameter from the scalar exchange contribution can be expressed as

$$\begin{aligned} \tau_{\text{NL}}^{\text{equil;SE}} = & \frac{2^{20\nu_s-42} k^{10\nu_s-18} \text{Cos}\left(\left[\nu_s - \frac{1}{2}\right] \frac{\pi}{2}\right)}{9\sqrt{3}} \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \frac{(1 - \epsilon_V - s_V^S)^8 H^8}{Y_S^5 c_s^6} \\ & \times \left\{ 9\mathbf{A}^2 \left[\Xi_1\left(-k, -k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) - \Xi_1\left(k, k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) \right] \right. \\ & + k^2 \mathbf{AB} \left[3 \left\{ \Xi_3\left(k, k, -\frac{2k}{\sqrt{3}}, \frac{2k}{\sqrt{3}}, k, k\right) - \Xi_3\left(-k, -k, -\frac{2k}{\sqrt{3}}, \frac{2k}{\sqrt{3}}, k, k\right) \right\} \right. \\ & + 4\sqrt{3} \left\{ \Xi_3\left(k, k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) - \Xi_3\left(-k, -k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) \right\} \\ & + 3 \left\{ \Xi_4\left(-\frac{2k}{\sqrt{3}}, k, k, k, k, \frac{2k}{\sqrt{3}}\right) - \Xi_4\left(-\frac{2k}{\sqrt{3}}, -k, -k, k, k, \frac{2k}{\sqrt{3}}\right) \right\} \\ & - 4\sqrt{3} \left\{ \Xi_4\left(k, k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) - \Xi_4\left(-k, -k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) \right\} \left. \right] \\ & - k^4 \mathbf{B}^2 \left[\left\{ \Xi_2\left(-\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}, k, k\right) - \Xi_2\left(-\frac{2k}{\sqrt{3}}, -k, -k, \frac{2k}{\sqrt{3}}, k, k\right) \right\} \right. \\ & + \frac{4}{\sqrt{3}} \left\{ \Xi_2\left(-\frac{2k}{\sqrt{3}}, k, k, k, k, \frac{2k}{\sqrt{3}}\right) - \Xi_2\left(-\frac{2k}{\sqrt{3}}, -k, -k, k, k, \frac{2k}{\sqrt{3}}\right) \right\} \\ & - \frac{4}{\sqrt{3}} \left\{ \Xi_2\left(k, k, -\frac{2k}{\sqrt{3}}, \frac{2k}{\sqrt{3}}, k, k\right) - \Xi_2\left(-k, -k, -\frac{2k}{\sqrt{3}}, \frac{2k}{\sqrt{3}}, k, k\right) \right\} \\ & - \frac{16}{3} \left\{ \Xi_2\left(k, k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) - \Xi_2\left(-k, -k, -\frac{2k}{\sqrt{3}}, k, k, \frac{2k}{\sqrt{3}}\right) \right\} \left. \right] \\ & + 23 \text{ permutations} \left. \right\}. \end{aligned} \quad (4.19)$$

4.3 Graviton exchange

In this section we are interested to evaluate the contribution of four-point function of curvature perturbations from the exchange of graviton. This process involves a third-order interaction among scalar fluctuations and tensor perturbations. To proceed, we need here only the significant third order term in the action, which describes the graviton-scalar-scalar vertex in the uniform gauge as

$$S_{\text{GE}} = \frac{1}{2} \int dt d^3x a^2 \mathcal{Y}_1 h_{ij} \zeta_{,i} \zeta_{,j}, \quad (4.20)$$

where $\mathcal{Y}_1 = Y_S c_s^2$. Using the in-in procedure the *four-point correlator function* for the quasi-exponential limit can be expressed in the following form:

$$\begin{aligned} & \langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4) \rangle^{\text{GE}} \\ & = -i \lim_{\eta^* \rightarrow 0} \int_{-\infty}^{\eta^*} d\eta \int_{-\infty}^{\eta} d\tilde{\eta} \\ & \langle 0 | [[\zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4), (H_{\text{int}}(\eta))_{\zeta\zeta\zeta}^{\text{GE}}], \\ & \quad \times (H_{\text{int}}(\tilde{\eta}))_{\zeta\zeta\zeta}^{\text{GE}}] | 0 \rangle \\ & = (2\pi)^3 \delta^{(3)}(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) \mathcal{T}_{\zeta}^{\text{GE}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4), \end{aligned} \quad (4.21)$$

where in the interaction picture the Hamiltonian can be written in terms of the third-order Lagrangian density as

$$(H_{\text{int}}(\eta))_{\zeta\zeta\zeta}^{\text{GE}} = - \int d^3x \mathcal{L}_3^{\text{GE}}.$$

Here following the ansatz used in [22] the *trispectrum* $\mathcal{T}_{\zeta}^{\text{GE}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4)$ obtained from the *graviton exchange* contribution is defined as

$$\begin{aligned} \mathcal{T}_{\zeta}^{\text{GE}}(\vec{k}_1, \vec{k}_2, \vec{k}_3, \vec{k}_4) = & \frac{1}{\prod_{i=1}^4 k_i^3} [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) \\ & + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) \\ & + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] \left\{ \tau_{\text{NL}}^{\text{GE}} P_{\zeta(1)}^3 \right. \\ & \left. + \frac{54}{25} g_{\text{NL}}^{\text{GE}} P_{\zeta(2)}^3 \right\}, \end{aligned} \quad (4.22)$$

where $\tau_{\text{NL}}^{\text{GE}}$ and $g_{\text{NL}}^{\text{GE}}$ are the two nonlinear parameters which carry the signatures of primordial non-Gaussianities of the curvature perturbation in the trispectrum analysis. By knowing $\tau_{\text{NL}}^{\text{GE}}$ the other parameter $g_{\text{NL}}^{\text{GE}}$ can be calculated by making use of the following relation [65]:

$$\begin{aligned} g_{\text{NL}}^{\text{GE}} = & \frac{64}{K^3} [(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3) \\ & \times (k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})] \tau_{\text{NL}}^{\text{GE}}, \end{aligned} \quad (4.23)$$

where $\vec{K} = k_1 + k_2 + k_3 + k_4$. The explicit form of $\tau_{\text{NL}}^{\text{GE}}$ characterizing the trispectrum obtained from the graviton exchange contribution can be expressed for our model as:

$$\tau_{\text{NL}}^{\text{GE}} = \lim_{\eta^* \rightarrow 0} \frac{2^{8\nu_s-31} \pi^2 (1 - \epsilon_V - s_V^S)^8 (1 - \epsilon_V - s_V^T)^2 \bar{K}^{10\nu_s-15} \text{Sin}^8 \left(\left[\nu_s - \frac{1}{2} \right] \frac{\pi}{2} \right) \text{Sin}^2 \left(\left[\nu_T - \frac{1}{2} \right] \frac{\pi}{2} \right)}{[(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})]} \\ \times \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{H^{10}}{Y_S^4 Y_T^2 c_s^{12} c_T^6} \left\{ \sum_{\substack{\lambda=+[+, -], \\ \times [+ , -]}} \sum_{i,j,l,m} \sum_{\substack{a < b \\ c < d \\ 23 \text{ perms.}}} \epsilon_{ij}^\lambda(\vec{k}_{ab}) \epsilon_{lm}^\lambda(\vec{k}_{cd}) \frac{k_a^i k_b^j k_c^l k_d^m}{k_{ab}^{\nu_T+3} (k_a k_b k_c k_d)^{2\nu_s}} \cdot \vartheta_{abcd}(\eta^*) \right\}. \quad (4.24)$$

The momentum dependent functions $\vartheta_{abcd}(\eta^*)$ are given in the Appendix. Here to write Eq. (4.24) we have used the fact that the exchange momentum dependent polarization tensor $\epsilon_{ij}^\lambda(\vec{k}_{ab})$ is a symmetric tensor and also the four-point correlator obtained from the graviton exchange is invariant under the exchange of the subscripts of the momenta, $a \leftrightarrow b$ and $c \leftrightarrow d$. Additionally in Eq. (4.24) the sum is performed only over different indices a, b, c, d , and we have extracted an overall symmetry factor of 4, which takes care of the exchanges $a \leftrightarrow b$ and $c \leftrightarrow d$. Rewriting the sums appearing in Eq. (4.24) we get the following reduced formula for the non-Gaussian parameter:

tor as $\vec{k}_a = k_a(\sin \theta_a \cos \phi_a, \sin \theta_a \sin \phi_a, \cos \theta_a)$, where $\cos \theta_a \equiv \vec{k}_a \cdot \vec{k}_{12}$ and $\cos \phi_a \equiv \vec{k}_a \cdot \vec{e}$. This implies

$$\epsilon_{ij}^+ k_1^i k_2^j = k_1 k_2 \sin \theta_1 \sin \theta_2 \cos(\phi_1 + \phi_2), \\ \epsilon_{ij}^\times k_1^i k_2^j = k_1 k_2 \sin \theta_1 \sin \theta_2 \sin(\phi_1 + \phi_2), \quad (4.27)$$

with an identical relation holding for $\epsilon_{ij}^+ k_3^i k_4^j$ and $\epsilon_{ij}^\times k_3^i k_4^j$, which will contribute to the polarization sum also. The projections of the momentum vectors \vec{k}_1 and \vec{k}_2 (similarly for \vec{k}_3 and \vec{k}_4) on the plane orthogonal to the exchange momentum vector \vec{k}_{12} (\vec{k}_{34}) have the same amplitude but opposite directions. Consequently we have two additional sets of constraint relationships given by

$$\tau_{\text{NL}}^{\text{GE}} = \frac{2^{8\nu_s-31} \pi^2 (1 - \epsilon_V - s_V^S)^8 (1 - \epsilon_V - s_V^T)^2 \bar{K}^{10\nu_s-15} \text{Sin}^8 \left(\left[\nu_s - \frac{1}{2} \right] \frac{\pi}{2} \right) \text{Sin}^2 \left(\left[\nu_T - \frac{1}{2} \right] \frac{\pi}{2} \right)}{[(k_1^3 k_2^3 + k_3^3 k_4^3)(k_{13}^{-3} + k_{14}^{-3}) + (k_1^3 k_4^3 + k_2^3 k_3^3)(k_{12}^{-3} + k_{13}^{-3}) + (k_1^3 k_3^3 + k_2^3 k_4^3)(k_{12}^{-3} + k_{14}^{-3})]} \\ \times \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{H^{10}}{Y_S^4 Y_T^2 c_s^{12} c_T^6} \left\{ \sum_{\substack{\lambda=+[+, -], \\ \times [+ , -]}} \sum_{i,j,l,m} \left[\epsilon_{ij}^\lambda(\vec{k}_{12}) \epsilon_{lm}^\lambda(\vec{k}_{34}) \frac{k_1^i k_2^j k_3^l k_4^m}{k_{12}^{\nu_T+3} (k_1 k_2 k_3 k_4)^{2\nu_s}} \cdot (\hat{\vartheta}_{1234} + \hat{\vartheta}_{3412}) \right. \right. \\ \left. \left. + \epsilon_{ij}^\lambda(\vec{k}_{13}) \epsilon_{lm}^\lambda(\vec{k}_{24}) \frac{k_1^i k_3^j k_2^l k_4^m}{k_{13}^{\nu_T+3} (k_1 k_3 k_2 k_4)^{2\nu_s}} \cdot (\hat{\vartheta}_{1324} + \hat{\vartheta}_{2413}) + \epsilon_{ij}^\lambda(\vec{k}_{14}) \epsilon_{lm}^\lambda(\vec{k}_{23}) \frac{k_1^i k_4^j k_2^l k_3^m}{k_{14}^{\nu_T+3} (k_1 k_4 k_2 k_3)^{2\nu_s}} \cdot (\hat{\vartheta}_{1423} + \hat{\vartheta}_{2314}) \right] \right\}, \quad (4.25)$$

where we define $\lim_{\eta^* \rightarrow 0} \vartheta_{abcd}(\eta^*) := \hat{\vartheta}_{abcd}$. There are divergent contributions in the limit $\eta^* \rightarrow 0$ that appear with a logarithmic dependence on the momenta, but the additive cumulative contributions of \mathcal{I}_{abcd} and \mathcal{I}_{cdab} give rise to a finite contribution at late times.

To represent Eq. (4.25) in a simpler form, let us start with the polarization sum $\sum_s \epsilon_{ij}^s(\vec{k}_{12}) \epsilon_{lm}^s(\vec{k}_{34}) k_1^i k_2^j k_3^l k_4^m$ in terms of the relative angles between the \vec{k}_a and \vec{k}_{12} . The polarization tensors ϵ_{ij}^s can be rewritten as

$$\epsilon_{ij}^+ = \vec{e}_i \otimes \vec{e}_j - \vec{\bar{e}}_i \otimes \vec{\bar{e}}_j, \quad \epsilon_{ij}^\times = \vec{e}_i \otimes \vec{\bar{e}}_j + \vec{\bar{e}}_i \otimes \vec{e}_j, \quad (4.26)$$

where \vec{e} and $\vec{\bar{e}}$ are orthogonal unit vectors perpendicular to exchange momentum vector \vec{k}_{12} . It is convenient to write the momentum vector \vec{k}_a in a spherical polar coordinate system having $\{\vec{e}, \vec{\bar{e}}, \vec{k}_{12}/k_{12}\}$ as a basis. In this coordinate system one can express the momentum vec-

$$k_2 \sin \theta_2 = k_1 \sin \theta_1 \quad \text{and} \quad \phi_2 = \phi_1 + \pi, \\ k_4 \sin \theta_4 = k_3 \sin \theta_3 \quad \text{and} \quad \phi_4 = \phi_3 + \pi. \quad (4.28)$$

Using these relations we get

$$\sum_s \epsilon_{ij}^s(\vec{k}_{ab}) \epsilon_{lm}^s(\vec{k}_{cd}) k_a^i k_b^j k_c^l k_d^m \\ = k_a^2 k_c^2 \sin^2 \theta_a \sin^2 \theta_c \cos 2\Upsilon_{ab,cd}, \quad (4.29)$$

where we define a new angular coordinate $\Upsilon_{ab,cd} \equiv \phi_a - \phi_c$ with $a = 1, (b, c) = 2, 3, 4, d = 3, 4$, and $b > a, d > c, a \neq b \neq c \neq d$, which physically represents the angle between the projections of the two momentum vectors \vec{k}_a and \vec{k}_c on the plane orthogonal to \vec{k}_{12} . Alternatively this can be interpreted as the angle between the two planes formed by the pair of momentum vectors $\{\vec{k}_1, \vec{k}_2\}$ and $\{\vec{k}_3, \vec{k}_4\}$. Thus, the expression for the non-Gaussian parameter calculated from the graviton exchange contribution from the trispectrum can be simplified to the following expression:

$$\begin{aligned}
\tau_{\text{NL}}^{\text{GE}} = & \frac{2^{8\nu_s-31}\pi^2(1-\epsilon_V-s_V^S)^8(1-\epsilon_V-s_V^T)^2\bar{K}^{10\nu_s-15}\text{Sin}^8\left(\left[\nu_s-\frac{1}{2}\right]\frac{\pi}{2}\right)\text{Sin}^2\left(\left[\nu_T-\frac{1}{2}\right]\frac{\pi}{2}\right)}{[(k_1^3k_2^3+k_3^3k_4^3)(k_{13}^{-3}+k_{14}^{-3})+(k_1^3k_4^3+k_2^3k_3^3)(k_{12}^{-3}+k_{13}^{-3})+(k_1^3k_3^3+k_2^3k_4^3)(k_{12}^{-3}+k_{14}^{-3})]} \\
& \times \left| \frac{\Gamma(\nu_s)}{\Gamma(\frac{3}{2})} \right|^8 \left| \frac{\Gamma(\nu_T)}{\Gamma(\frac{3}{2})} \right|^2 \frac{H^{10}}{Y_S^4 Y_T^2 c_s^{12} c_T^6} \left\{ \frac{k_1^2 k_3^2 [1 - (\hat{k}_1 \cdot \hat{k}_{12})^2][1 - (\hat{k}_3 \cdot \hat{k}_{12})^2]}{k_{12}^{\nu_T+3} (k_1 k_2 k_3 k_4)^{2\nu_s}} \cos 2\Upsilon_{12,34} \cdot (\hat{\vartheta}_{1234} + \hat{\vartheta}_{3412}) \right. \\
& + \frac{k_1^2 k_2^2 [1 - (\hat{k}_1 \cdot \hat{k}_{13})^2][1 - (\hat{k}_2 \cdot \hat{k}_{13})^2]}{k_{13}^{\nu_T+3} (k_1 k_3 k_2 k_4)^{2\nu_s}} \cos 2\Upsilon_{13,24} \cdot (\hat{\vartheta}_{1324} + \hat{\vartheta}_{2413}) \\
& \left. + \frac{k_1^2 k_2^2 [1 - (\hat{k}_1 \cdot \hat{k}_{14})^2][1 - (\hat{k}_2 \cdot \hat{k}_{14})^2]}{k_{14}^{\nu_T+3} (k_1 k_4 k_2 k_3)^{2\nu_s}} \cos 2\Upsilon_{14,23} \cdot (\hat{\vartheta}_{1423} + \hat{\vartheta}_{2314}) \right\}. \quad (4.30)
\end{aligned}$$

Further, incorporating the contribution from the maximum shape of the trispectrum one can show that the graviton exchange contribution does not contribute anything in the equilateral limit. Now summing up all the significant contributions of the four-point four-scalar correlation coming from the *contact interaction*, *scalar exchange*, and *graviton exchange interaction* the numerical value of $\tau_{\text{NL}}^{\text{equil}}$ in the equilateral limit is obtained from our setup as $48 < \tau_{\text{NL}}^{\text{equil}} < 97$ in the quasi-exponential limit within the window for tensor-to-scalar ratio $0.213 < r < 0.250$ which is significantly large from other class of DBI models and consistent with the combined constraint obtained from the *Planck* + *WMAP9* + *high-L* + *BICEP2* [2–5] data.

5 Four-point consistency conditions and violation of Suyama–Yamaguchi relation

In the *counter-collinear limit* collecting the contribution from the *scalar exchange* diagram we derive the following expression for the four-point consistency condition:

$$\begin{aligned}
\langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4) \rangle^{\text{SE}} \approx & (2\pi)^3 \delta^3(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) \\
& \times \frac{(n_\zeta - 1)^2}{4} P_\zeta(k_{12}) P_\zeta(k_1) [P_\zeta(k_3) + \dots], \quad (5.1)
\end{aligned}$$

which can be interpreted as the *scalar exchange* contribution arising from the product of two back-to-back bispectra in the squeezed limit. Additionally, we consider the contribution from the *graviton exchange* diagram from which we derive another expression for the four-point consistency condition:

$$\begin{aligned}
\langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4) \rangle^{\text{GE}} \approx & 9c_s \epsilon_s (2\pi)^3 \delta^3 \\
& (\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) P_\zeta(k_{12}) P_\zeta(k_1) \\
& \times \left[\sum_{\substack{\lambda=[+, -], \\ \times[+, -]}} \sum_{i,j,l,m} \epsilon_{ij}^\lambda(\vec{k}_{12}) \epsilon_{lm}^\lambda(\vec{k}_{34}) \frac{k_1^i k_1^j k_3^l k_3^m}{k_1^2 k_3^2} P_\zeta(k_3) + \dots \right]. \quad (5.2)
\end{aligned}$$

Here using $k_{12} \rightarrow 0$, $\theta_1, \theta_3 \rightarrow \pi$ the polarization sum appearing in Eq. (5.2) can be simplified to the following expression:

$$\sum_{\substack{\lambda=[+, -], \\ \times[+, -]}} \sum_{i,j,l,m} \epsilon_{ij}^\lambda(\vec{k}_{12}) \epsilon_{lm}^\lambda(\vec{k}_{34}) \frac{k_1^i k_1^j k_3^l k_3^m}{k_1^2 k_3^2} = \cos 2\Upsilon_{12,34}. \quad (5.3)$$

Further substituting Eq. (5.3) in Eq. (5.2) and using Eq. (3.15) the four-point correlation function from the *graviton exchange* contribution in the counter-collinear limit ($k_{12} \ll k_1 \approx k_2, k_3 \approx k_4$) reduces to the following expression:

$$\begin{aligned}
\langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(\vec{k}_3) \zeta(\vec{k}_4) \rangle^{\text{GE}} = & 9 \cdot 2^{2(\nu_s - \nu_T - 4)} r_\star \\
& \left[1 + \frac{3}{2} \mathcal{O}(\epsilon_T^2) \right]_\star \left(\frac{1 - \epsilon_V - s_V^S}{1 - \epsilon_V - s_V^T} \right)_\star^2 \left| \frac{\Gamma(\nu_s)}{\Gamma(\nu_T)} \right|^2 \\
& \times (2\pi)^3 \delta^3(\vec{k}_1 + \vec{k}_2 + \vec{k}_3 + \vec{k}_4) P_\zeta(k_{12}) P_\zeta(k_1) \\
& \times [\cos 2\Upsilon_{12,34} P_\zeta(k_3) + \dots]. \quad (5.4)
\end{aligned}$$

To check the validity of the well-known *Suyama–Yamaguchi* consistency relation we start with the in–in picture where the four-point correlator can be written as

$$\langle \zeta^2(\vec{x}) \zeta^2(0) \rangle_{\vec{k}} = \sum_n |\langle n_{\vec{k}} | \zeta^2(0) \rangle|^2, \quad (5.5)$$

where n is a label for the individual states or particle number within the momentum eigenspace. Here the sum is written over positive definite terms. On the other hand in this context one of the contributions is the square of the squeezed limit of the three-point correlation function of the scalar contribution. This implies

$$\langle \zeta^2(\vec{x}) \zeta^2(0) \rangle_{\vec{k}} = \frac{|\langle \zeta(\vec{k}) | \zeta^2(0) \rangle|^2}{P_\zeta(k)} + \sum_{\vec{n}} |\langle \vec{n}_{\vec{k}} | \zeta^2(0) \rangle|^2. \quad (5.6)$$

As the second term in Eq. (5.6) is always positive definite we conclude that $\langle \zeta^2(\vec{x}) \zeta^2(0) \rangle_{\vec{k}} \geq \frac{|\langle \zeta(\vec{k}) | \zeta^2(0) \rangle|^2}{P_\zeta(k)}$. Further using this result in the quasi-exponential limit we get

$$\lim_{q \rightarrow 0} \int_{\vec{k}_1} \frac{d^3 k_1}{(2\pi)^3} \int_{\vec{k}_3} \frac{d^3 k_3}{(2\pi)^3} \langle \zeta(\vec{k}_1) \zeta(\vec{q} - \vec{k}_1) \zeta(\vec{k}_3) \zeta(-\vec{q} - \vec{k}_3) \rangle$$

$$\geq \lim_{q \rightarrow 0} \frac{\left| \int_{\vec{k}_2} \frac{d^3 k_2}{(2\pi)^3} \langle \zeta(\vec{k}_1) \zeta(\vec{k}_2) \zeta(-\vec{q} - \vec{k}_2) \rangle \right|^2}{P_\zeta(q)}.$$
(5.7)

Hence using Eq. (5.7) finally we get

$$\lim_{q \rightarrow 0} \int_{\vec{k}_1} \frac{d^3 k_1}{(2\pi)^3} \int_{\vec{k}_3} \frac{d^3 k_3}{(2\pi)^3} P_\zeta(k_1) P_\zeta(k_2) \left\{ \tau_{\text{NL}} - \frac{36}{25} (f_{\text{NL}})^2 \right\} \geq 0,$$
(5.8)

resulting in a generic outcome of the DBI Galileon inflation, viz.,

$$\hat{\tau}_{\text{NL}} \geq \frac{36}{25} (\hat{f}_{\text{NL}})^2$$
(5.9)

where $\hat{\tau}_{\text{NL}}$ and \hat{f}_{NL} are used to represent the soft limits of the three- and four-point correlator functions. This relation directly confirms the partial violation of the *standard Suyama–Yamaguchi relation* [61, 62, 64] $\hat{\tau}_{\text{NL}} = \frac{36}{25} (\hat{f}_{\text{NL}})^2$. These nontrivial features allow us to go beyond the no-go theorem in the present context. Some other aspects of the violation of the well-known *consistency relations* in the context of single field inflation have been studied in [65, 66].

Let us now investigate some possible explanations of the partial violation of the *standard Suyama–Yamaguchi relation*. The standard relations and limits of Non-Gaussianity are usually derived under the following assumptions:

- The background is Einsteinian gravity.
- Inflation is driven by a single scalar field.
- The scalar field action is canonical.
- Perfect slow-roll conditions hold good throughout.
- The vacuum is Bunch–Davies.

Of course, most of the results derived using these assumptions are true to a great extent; it is not obvious that they will still hold good if one or more assumptions are relaxed. Only when one deals with a context where one has to relax one or more assumptions, one can investigate the consequences and conclude if the relations are still valid or not. In the present scenario, a non-Einstein framework forms the background along with a non-canonical action appearing in the matter sector for a DBI Galileon. The contributions of them arise through the first two terms of Eq. (2.4) which will further effect Eqs. (5.1) and (5.4). On top of that, we have higher

derivative contributions for the DBI Galileon matter sector, for the contact interaction, and scalar and graviton exchange contributions are coupled with the higher curvature contributions through highly nonlinear terms as appearing in the perturbative action as mentioned in Eqs. (4.2), (4.13), and (4.20), which directly affects the interaction vertex factors as well as the propagators of the setup, resulting in a deviation from the standard results. We suspect that these *non-standard* inputs might have reflected in the violation of the no-go theorem.

Having said this, we do admit that this can at best serve as a qualitative explanation of the violation. A huge amount of work needs to be done before one can comment conclusively on the deviation from which the assumption still respects the relation and the deviation which leads to violation, and, in case it does, to what extent. This is a highly nontrivial task which one can only hope to attempt in the future.

6 Summary and outlook

In this article we have explored primordial non-Gaussian features of the DBI Galileon inflation in the D3 brane. We have derived the expressions for three- and four-point correlator functions in terms of the nonlinear parameters f_{NL} and τ_{NL} for the equilateral type of non-Gaussian configurations in the nontrivial polarization modes. This resulted in a significantly large value for the non-Gaussianity from this setup. We could also find a parameter space for both non-Gaussianity and the tensor-to-scalar ratio (r) consistent with the combined constraint obtained from the *Planck+WMAP9+high-L+BICEP2* data. The detectable features of primordial non-Gaussianity lead to the conclusion that this type of models can directly be verified by upcoming data. Moreover, the calculations reveal some other interesting results like a partial violation of the *Suyama–Yamaguchi* four-point consistency relation.

Some issues which can be addressed in the context of non-Gaussianity for the DBI Galileon are studies of mass spectrum of primordial black hole formation [67, 68] as a tool for constraining non-Gaussianity at small scales; the effect of the presence of one loop and two loop radiative corrections in the presence of all possible scalar and tensor mode fluctuations in the bispectrum and trispectrum; the study of different shapes in equilateral, local, orthogonal, squeezed limit configuration for the tree, one and two loop level of non-Gaussianity and calculation of other higher-order n -point correlation functions to find the proper consistency relations between all higher-order non-Gaussian parameters as well as the analysis of CMB bispectrum and trispectrum in the presence of a Galileon in a SUGRA background. Given the promising results of the present paper, these open issues are worth exploring in the future as they may give rise to interesting results.

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Appendix

In this section we mention all the momentum dependent functions appearing in the context of the bispectrum and trispectrum analysis coming from all scalar-tensor three-point correlators and the four-point scalar correlation.

A. Functions appearing in three-scalar correlation

The functions appearing in the context of the three-scalar correlation can be expressed as

In the equilateral configuration these functions are related through the following expression:

$$\begin{aligned}\mathcal{I}_1^{\text{equil}}(x) &= \mathcal{I}_5^{\text{equil}}(x) = \frac{\mathcal{I}_4^{\text{equil}}(x)}{2}, \quad \mathcal{I}_2^{\text{equil}}(x) = \frac{3\mathcal{I}_8^{\text{equil}}(x)}{2(1-x)}, \\ \mathcal{I}_6^{\text{equil}}(x) &= \left(1 + \frac{x}{2}\right) \mathcal{I}_3^{\text{equil}}(x).\end{aligned}\quad (6.2)$$

Additionally in the squeezed limit these functions are reduced to the following expressions:

$$\begin{aligned}\mathcal{I}_1(x) &= \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \Gamma(1+x) \left[\frac{2+x}{K} \sum_{i>j} k_i^2 k_j^2 - \frac{1+x}{K^2} \sum_{i \neq j} k_i^2 k_j^3 \right], \\ \mathcal{I}_2(x) &= \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \Gamma(1+x) \left[\frac{K}{1-x} - \frac{1}{K} \sum_{i>j} k_i k_j - \frac{1+x}{K^2} k_1 k_2 k_3 \right], \quad \mathcal{I}_3(x) = \frac{(k_1 k_2 k_3)^3}{K^3} \frac{\Gamma(3+x)}{2} \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right), \\ \mathcal{I}_4(x) &= \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \left\{ \frac{(\vec{k}_1 \cdot \vec{k}_2) k_3^2}{K} \left[(3+x) \Gamma(1+x) - \Gamma(2+x) \frac{k_3}{K} \right] + \frac{(\vec{k}_2 \cdot \vec{k}_3) k_1^2}{K} \left[(3+x) \Gamma(1+x) - \Gamma(2+x) \frac{k_1}{K} \right] \right. \\ &\quad \left. + \frac{(\vec{k}_3 \cdot \vec{k}_1) k_2^2}{K} \left[(3+x) \Gamma(1+x) - \Gamma(2+x) \frac{k_2}{K} \right] \right\}, \\ \mathcal{I}_5(x) &= \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \left\{ \frac{(\vec{k}_1 \cdot \vec{k}_2) k_3^2}{K} \left[\Gamma(1+x) + \Gamma(2+x) \frac{k_3}{K} \right] + \frac{(\vec{k}_2 \cdot \vec{k}_3) k_1^2}{K} \left[\Gamma(1+x) + \Gamma(2+x) \frac{k_1}{K} \right] \right. \\ &\quad \left. + \frac{(\vec{k}_3 \cdot \vec{k}_1) k_2^2}{K} \left[\Gamma(1+x) + \Gamma(2+x) \frac{k_2}{K} \right] \right\}, \\ \mathcal{I}_6(x) &= \frac{(k_1 k_2 k_3)^2}{K^3} \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \frac{(6+x) \Gamma(3+x)}{12}, \\ \mathcal{I}_7(x) &= \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \frac{2+x}{2} \left[\Gamma(1+x) + \Gamma(2+x) \left(\frac{k_1 k_2 + k_2 k_3 + k_3 k_1}{K^2} + (3+x) \frac{k_1 k_2 k_3}{K^3} \right) \right] \left\{ \frac{(\vec{k}_1 \cdot \vec{k}_2) k_3^2}{K} + \frac{(\vec{k}_2 \cdot \vec{k}_3) k_1^2}{K} + \frac{(\vec{k}_3 \cdot \vec{k}_1) k_2^2}{K} \right\}, \\ \mathcal{I}_8(x) &= \text{Cos}\left(\left[x - \frac{1}{2}\right] \frac{\pi}{2}\right) \left\{ \frac{(\vec{k}_1 \cdot \vec{k}_2) k_3^2}{K} \left[(3+x) \Gamma(1+x) + (3+x) \Gamma(2+x) \frac{k_3}{K} - \Gamma(3+x) \frac{k_3^2}{K^2} \right] + \frac{(\vec{k}_2 \cdot \vec{k}_3) k_1^2}{K} \left[(3+x) \Gamma(1+x) \right. \right. \\ &\quad \left. \left. + (3+x) \Gamma(2+x) \frac{k_1}{K} - \Gamma(3+x) \frac{k_1^2}{K^2} \right] + \frac{(\vec{k}_3 \cdot \vec{k}_1) k_2^2}{K} \left[(3+x) \Gamma(1+x) + (3+x) \Gamma(2+x) \frac{k_2}{K} - \Gamma(3+x) \frac{k_2^2}{K^2} \right] \right\}.\end{aligned}\quad (6.1)$$

$$\begin{aligned}
\mathcal{I}_1^{\text{sq}} &= \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) k_1^3 \Gamma(1+x) \left[\frac{2+x}{2} - \frac{(1+x)}{2} \right], \quad \mathcal{I}_2^{\text{sq}} = \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) \Gamma(1+x) \left[\frac{2k_1}{1-x} - \frac{k_1}{2} - \frac{1+x}{4} k_3 \right], \\
\mathcal{I}_3^{\text{sq}} &= \frac{(k_1 k_3)^3}{8} \frac{\Gamma(3+x)}{2} \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right), \quad \mathcal{I}_6^{\text{sq}} = \frac{k_1 k_3^2}{8} \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) \frac{(6+x)\Gamma(3+x)}{12}, \\
\mathcal{I}_4^{\text{sq}} &= \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) \left\{ \frac{k_1 k_3^2}{2} \left[(3+x)\Gamma(1+x) - \Gamma(2+x) \frac{k_3}{2k_1} \right] + (\vec{k}_1 \cdot \vec{k}_3) k_1 \left[(3+x)\Gamma(1+x) - \Gamma(2+x) \frac{1}{2} \right] \right\}, \\
\mathcal{I}_5^{\text{sq}} &= \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) \left\{ \frac{k_1 k_3^2}{2} \left[\Gamma(1+x) + \Gamma(2+x) \frac{k_3}{2k_1} \right] + \frac{(\vec{k}_1 \cdot \vec{k}_3) k_1^2}{k_1} \left[\Gamma(1+x) + \Gamma(2+x) \frac{k_1}{K} \right] \right\}, \\
\mathcal{I}_7^{\text{sq}} &= \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) \frac{2+x}{2} \left[\Gamma(1+x) + \Gamma(2+x) \left(\frac{1}{4} + (3+x) \frac{k_3}{8k_1} \right) \right] \left\{ \frac{k_1 k_3^2}{2} + (\vec{k}_1 \cdot \vec{k}_3) k_1 \right\}, \\
\mathcal{I}_8^{\text{sq}} &= \text{Cos} \left(\left[x - \frac{1}{2} \right] \frac{\pi}{2} \right) \left\{ \frac{k_1 k_3^2}{2} \left[(3+x)\Gamma(1+x) + (3+x)\Gamma(2+x) \frac{k_3}{2k_1} - \Gamma(3+x) \frac{k_3^2}{4k_1^2} \right] \right. \\
&\quad \left. + (\vec{k}_1 \cdot \vec{k}_3) k_1 \left[(3+x)\Gamma(1+x) + (3+x)\Gamma(2+x) \frac{1}{2} - \Gamma(3+x) \frac{1}{4} \right] \right\}.
\end{aligned} \tag{6.3}$$

B. Functions appearing in the one-scalar two-tensor correlation

The functional dependence of the coefficients appearing in the context of the one-scalar two-tensor correlation can be expressed as

$$\begin{aligned}
(\nabla_1)_{ij;kl}^u &= \sum_{p=1}^6 \left\{ \frac{[\mathcal{J}_p(\vec{k}_1, \vec{k}_2, \vec{k}_3)]_{ij;kl}^u}{k_1^{v_s} (k_2 k_3)^{v_T}} + \frac{[\mathcal{J}_p(\vec{k}_2, \vec{k}_1, \vec{k}_3)]_{ij;kl}^u}{k_2^{v_s} (k_1 k_3)^{v_T}} + \frac{[\mathcal{J}_p(\vec{k}_3, \vec{k}_2, \vec{k}_1)]_{ij;kl}^u}{k_3^{v_s} (k_2 k_1)^{v_T}} \right\} \frac{\Gamma(7+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-\frac{7}{3}} c_T^{4v_T-\frac{2p}{3}-\frac{14}{3}} \underline{K}^{7+p-4v_T-2v_s}}, \\
(\nabla_2)_{ij;kl}^u &= \frac{\left[\frac{(\vec{k}_1 \cdot \vec{k}_2)}{k_1^{v_s} (k_2 k_3)^{v_T}} + \frac{(\vec{k}_2 \cdot \vec{k}_3)}{k_2^{v_s} (k_1 k_3)^{v_T}} + \frac{(\vec{k}_3 \cdot \vec{k}_1)}{k_3^{v_s} (k_2 k_1)^{v_T}} \right]}{\left(\frac{3}{2} - v_T \right)^2 c_T^2} \sum_{p=1}^4 H_p \frac{\Gamma(9+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-3} c_T^{4v_T-\frac{2p}{3}-6} \underline{K}^{9+p-4v_T-2v_s}} \mathcal{N}_{ij;kl}^u, \\
(\nabla_3)_{ij;kl}^u &= \frac{[(\vec{k}_1 \cdot \vec{k}_2) Y_{123} + (\vec{k}_1 \cdot \vec{k}_3) Y_{132} + (\vec{k}_2 \cdot \vec{k}_3) Y_{213} + (\vec{k}_2 \cdot \vec{k}_1) Y_{231} + (\vec{k}_3 \cdot \vec{k}_2) Y_{312} + (\vec{k}_3 \cdot \vec{k}_1) Y_{321}] \mathcal{N}_{ij;kl}^u}{\left(\frac{3}{2} - v_T \right)^2 c_T^2}, \\
(\nabla_4)_{ij;kl}^u &= \left(\frac{3}{2} - v_s \right) [\tilde{\mathcal{J}}_{123} + \tilde{\mathcal{J}}_{132} + \tilde{\mathcal{J}}_{213} + \tilde{\mathcal{J}}_{231} + \tilde{\mathcal{J}}_{312} + \tilde{\mathcal{J}}_{321}] \mathcal{N}_{ij;kl}^u, \\
(\nabla_5)_{ij;kl}^u &= [\tilde{\mathcal{C}}_{123} + \tilde{\mathcal{C}}_{132} + \tilde{\mathcal{C}}_{213} + \tilde{\mathcal{C}}_{231} + \tilde{\mathcal{C}}_{312} + \tilde{\mathcal{C}}_{321}]_{ij;kl}^u, \\
(\nabla_6)_{ij;kl}^u &= [\hat{\mathcal{W}}_{123} + \hat{\mathcal{W}}_{132} + \hat{\mathcal{W}}_{213} + \hat{\mathcal{W}}_{231} + \hat{\mathcal{W}}_{312} + \hat{\mathcal{W}}_{321}] \mathcal{N}_{ij;kl}^u, \\
(\nabla_7)_{ij;kl}^u &= [k_{1m} k_{1m'} \{\bar{X}_{123} + \bar{X}_{132}\} + k_{2m} k_{2m'} \{\bar{X}_{231} + \bar{X}_{213}\} + k_{3m} k_{3m'} \{\bar{X}_{312} + \bar{X}_{321}\}] \mathcal{N}_{ij;kl}^u \mathcal{N}_{mn,m'n}^u,
\end{aligned} \tag{6.4}$$

with

$$\begin{aligned}
 \left[\mathcal{J}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u &= \mathcal{N}_{ij,kl}^u \left(\frac{3}{2} - v_T \right)^2, \left[\mathcal{J}_2(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u = \left[\mathcal{J}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u \underline{K} c_s^{-\frac{1}{3}} c_T^{-\frac{2}{3}}, \\
 \left[\mathcal{J}_3(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u &= \mathcal{N}_{ij,kl}^u \left(\frac{3}{2} - v_T \right) \left[(k_a^2 + k_b^2 + k_a k_b) + \left(\frac{3}{2} - v_T \right) k_a (k_b + k_c) \right] \\
 \left[\mathcal{J}_4(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u &= \mathcal{N}_{ij,kl}^u \left(\frac{3}{2} - v_T \right) \left[k_b k_c (k_b + k_c) + k_a (k_b^2 + k_c^2 + k_b k_c) \right], \\
 \left[\mathcal{J}_5(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u &= \mathcal{N}_{ij,kl}^u \left[k_b^2 k_c^2 + k_a k_b k_c (k_b + k_c) \right], \left[\mathcal{J}_6(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u = i \mathcal{N}_{ij,kl}^u k_a k_b^2 k_c^2, \\
 &\text{(includes 3 permutations of } a, b, c),
 \end{aligned} \tag{6.5}$$

$$\begin{aligned}
 Y_{abc} &= \frac{1}{k_a^{v_s} (k_b k_c)^{v_T}} \left\{ \sum_{p=1}^4 H_p \frac{\Gamma(9+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-3} c_T^{4v_T-\frac{2p}{3}-6} \underline{K}^{9+p-4v_T-2v_s}} + \sum_{q=1}^5 \mathcal{A}_q^{abc} \frac{\Gamma(8+q-4v_T-2v_s)}{c_s^{2v_s-\frac{q}{3}-\frac{8}{3}} c_T^{4v_T-\frac{2q}{3}-\frac{16}{3}} \underline{K}^{8+q-4v_T-2v_s}} \right\} \\
 &\text{(with } a, b, c = 1, 2, 3 \text{ with } a \neq b \neq c), \\
 H_1 = H_2 = L_1, H_3 &= \frac{H_1 (k_a k_b + k_b k_c + k_c k_a)}{c_s^{-\frac{2}{3}} c_T^{-\frac{4}{3}} \underline{K}^2}, H_4 = -\frac{k_a k_b k_c}{c_s^{-1} c_T^{-2} \underline{K}^3}, \\
 \mathcal{A}_1^{abc} &= \frac{a^2 Y_s c_s^2}{t_1} \left(\frac{3}{2} - v_s \right)^2, \mathcal{A}_2^{abc} = c_s^{-\frac{1}{3}} c_T^{-\frac{2}{3}} \underline{K} \mathcal{A}_1^{abc}, \mathcal{A}_3^{abc} = -\left(k_a k_b + k_b k_c + k_c k_a + k_a^2 \right) \mathcal{A}_1^{abc}, \\
 \mathcal{A}_4^{abc} &= -\frac{a^2 Y_s c_s^2}{t_1} \left(\frac{3}{2} - v_s \right) \left[k_a k_b k_c \left(\frac{3}{2} - v_s \right) + k_a^2 (k_b + k_c) \right], \mathcal{A}_5^{abc} = \frac{a^2 Y_s c_s^2}{t_1} k_a^2 k_b k_c, \\
 [\tilde{\mathcal{C}}_{abc}]_{ij;kl}^u &= \sum_{p=1}^6 \frac{\left[\mathcal{J}_p(\vec{k}_a, \vec{k}_b, \vec{k}_c) \right]_{ij;kl}^u}{k_a^{v_s} (k_b k_c)^{v_T}} \frac{\Gamma(7+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-\frac{7}{3}} c_T^{4v_T-\frac{2p}{3}-\frac{14}{3}} \underline{K}^{7+p-4v_T-2v_s}} \quad \text{(includes 6 permutations of } a, b, c), \\
 \hat{\mathcal{W}}_{abc} &= \frac{1}{k_a^{v_s} (k_b k_c)^{v_T}} \left\{ k_a^2 \frac{\Gamma(8-4v_T-2v_s)}{c_s^{2v_s-\frac{8}{3}} c_T^{4v_T-\frac{16}{3}} \underline{K}^{8-4v_T-2v_s}} + \frac{a^2 Y_s c_s^2}{t_1} \sum_{p=1}^7 a_p^{abc} \frac{\Gamma(6+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-2} c_T^{4v_T-\frac{2p}{3}-4} \underline{K}^{6+p-4v_T-2v_s}} \right\}, \\
 \bar{X}_{abc} &= \sum_{p=1}^7 \frac{a_p^{abc}}{k_a^{v_s} (k_b k_c)^{v_T}} \frac{\Gamma(7+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-\frac{7}{3}} c_T^{4v_T-\frac{2p}{3}-\frac{14}{3}} \underline{K}^{7+p-4v_T-2v_s}}, \\
 \tilde{J}_{abc} &= \sum_{p=1}^7 \frac{a_p^{abc}}{k_a^{v_s} (k_b k_c)^{v_T}} \frac{\Gamma(6+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-2} c_T^{4v_T-\frac{2p}{3}-4} \underline{K}^{6+p-4v_T-2v_s}}, a_1^{abc} = \left(\frac{3}{2} - v_T \right)^2 \left(\frac{3}{2} - v_s \right), a_2^{abc} = a_1^{abc} c_s^{-\frac{1}{3}} c_T^{-\frac{2}{3}} \underline{K}, \\
 a_3^{abc} &= \left(\frac{3}{2} - v_T \right) \left(\frac{3}{2} - v_s \right) \left[k_a (k_b + k_c) + k_b^2 + k_c^2 + k_b k_c \right] + \left(\frac{3}{2} - v_T \right)^2 k_a^2, \\
 a_4^{abc} &= \left[k_a^2 (k_b + k_c) \left(\frac{3}{2} - v_T \right) + \left\{ k_a (k_b^2 + k_c^2 + k_b k_c) + k_b k_c (k_b + k_c) \right\} \left(\frac{3}{2} - v_T \right) \left(\frac{3}{2} - v_s \right) \right], \\
 a_5^{abc} &= \left[\left(\frac{3}{2} - v_T \right) k_a^2 (k_b^2 + k_c^2 + k_b k_c) + \left(\frac{3}{2} - v_s \right) k_b^2 k_c^2 + \left(\frac{3}{2} - v_T \right) \left(\frac{3}{2} - v_s \right) k_a k_b k_c (k_b + k_c) \right], \\
 a_6^{abc} &= k_a k_b k_c \left[\left(\frac{3}{2} - v_T \right) k_b k_c + \left(\frac{3}{2} - v_s \right) k_a (k_b + k_c) \right], a_7^{abc} = -k_a^2 k_b^2 k_c^2.
 \end{aligned} \tag{6.6}$$

After using the basis transformation mentioned in Eq. (3.23) the reduced form of the above mentioned coefficients can be expressed in the following form:

$$\begin{aligned}
(\nabla_1)^{u;\lambda_2;\lambda_3} &= \sum_{p=1}^6 \left\{ \frac{[\mathcal{J}_p(\vec{k}_1, \vec{k}_2, \vec{k}_3)]^{u;\lambda_2;\lambda_3}}{k_1^{v_s}(k_2 k_3)^{v_T}} + \frac{[\mathcal{J}_p(\vec{k}_2, \vec{k}_1, \vec{k}_3)]^{u;\lambda_2;\lambda_3}}{k_2^{v_s}(k_1 k_3)^{v_T}} + \frac{[\mathcal{J}_p(\vec{k}_3, \vec{k}_2, \vec{k}_1)]^{u;\lambda_2;\lambda_3}}{k_3^{v_s}(k_2 k_1)^{v_T}} \right\} \\
&\quad \times \frac{\Gamma(7+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-\frac{7}{3}} c_T^{4v_T-\frac{2p}{3}-\frac{14}{3}} \underline{K}^{7+p-4v_T-2v_s}}, \\
(\nabla_2)^{u;\lambda_2;\lambda_3} &= \frac{2 \left[\frac{(\vec{k}_1, \vec{k}_2)}{k_1^{v_s}(k_2 k_3)^{v_T}} + \frac{(\vec{k}_2, \vec{k}_3)}{k_2^{v_s}(k_1 k_3)^{v_T}} + \frac{(\vec{k}_3, \vec{k}_1)}{k_3^{v_s}(k_1 k_2)^{v_T}} \right]^{u;\lambda_2;\lambda_3}}{\left(\frac{3}{2} - v_T\right)^2 c_T^2} \sum_{p=1}^4 H_p \frac{\Gamma(9+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-3} c_T^{4v_T-\frac{2p}{3}-6} \underline{K}^{9+p-4v_T-2v_s}}, \\
(\nabla_3)^{u;\lambda_2;\lambda_3} &= \frac{2[(\vec{k}_1, \vec{k}_2)Y_{123} + (\vec{k}_1, \vec{k}_3)Y_{132} + (\vec{k}_2, \vec{k}_3)Y_{213} + (\vec{k}_2, \vec{k}_1)Y_{231} + (\vec{k}_3, \vec{k}_2)Y_{312} + (\vec{k}_3, \vec{k}_1)Y_{321}]^{u;\lambda_2;\lambda_3}}{\left(\frac{3}{2} - v_T\right)^2 c_T^2}, \tag{6.7}
\end{aligned}$$

$$(\nabla_4)^{u;\lambda_2;\lambda_3} = 2 \left(\frac{3}{2} - v_s \right) [\tilde{\mathcal{J}}_{123} + \tilde{\mathcal{J}}_{132} + \tilde{\mathcal{J}}_{213} + \tilde{\mathcal{J}}_{231} + \tilde{\mathcal{J}}_{312} + \tilde{\mathcal{J}}_{321}] \delta^{\lambda_2 \lambda_3},$$

$$(\nabla_5)^{u;\lambda_2;\lambda_3} = [\tilde{\mathcal{C}}_{123} + \tilde{\mathcal{C}}_{132} + \tilde{\mathcal{C}}_{213} + \tilde{\mathcal{C}}_{231} + \tilde{\mathcal{C}}_{312} + \tilde{\mathcal{C}}_{321}]^{u;\lambda_2;\lambda_3},$$

$$(\nabla_6)^{u;\lambda_2;\lambda_3} = 2[\hat{\mathcal{W}}_{123} + \hat{\mathcal{W}}_{132} + \hat{\mathcal{W}}_{213} + \hat{\mathcal{W}}_{231} + \hat{\mathcal{W}}_{312} + \hat{\mathcal{W}}_{321}] \delta^{\lambda_2 \lambda_3},$$

$$(\nabla_7)^{u;\lambda_2;\lambda_3} = [Z_1^{u;\lambda_2;\lambda_3} \{\bar{X}_{123} + \bar{X}_{132}\} + Z_2^{u;\lambda_2;\lambda_3} \{\bar{X}_{231} + \bar{X}_{213}\} + Z_3^{u;\lambda_2;\lambda_3} \{\bar{X}_{312} + \bar{X}_{321}\}],$$

with

$$\begin{aligned}
[\mathcal{J}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} &= 2 \left(\frac{3}{2} - v_T \right)^2, \quad [\mathcal{J}_2(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} = [\mathcal{J}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} c_s^{-\frac{1}{3}} c_T^{-\frac{2}{3}} \underline{K}, \\
[\mathcal{J}_3(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} &= 2\lambda_2\lambda_3 \left(\frac{3}{2} - v_T \right) [(k_a^2 + k_b^2 + k_a k_b) + \left(\frac{3}{2} - v_T \right) k_a(k_b + k_c)] \\
[\mathcal{J}_4(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} &= 2 \left(\frac{3}{2} - v_T \right) [\lambda_2^3 k_b k_c (k_b + k_c) + \lambda_3^3 k_a (k_b^2 + k_c^2 + k_b k_c)], \\
[\mathcal{J}_5(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} &= 2\lambda_2^2 \lambda_3^2 [k_b^2 k_c^2 + k_a k_b k_c (k_b + k_c)], \quad [\mathcal{J}_6(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3} = 2i\lambda_3^2 \lambda_2^2 k_a k_b^2 k_c^2, \\
&\quad \text{(includes 3 permutations of } a, b, c), \\
[\tilde{\mathcal{C}}_{abc}]^{u;\lambda_2;\lambda_3} &= \sum_{p=1}^6 \frac{[\mathcal{J}_p(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^{u;\lambda_2;\lambda_3}}{k_a^{v_s}(k_b k_c)^{v_T}} \frac{\Gamma(7+p-4v_T-2v_s)}{c_s^{2v_s-\frac{p}{3}-\frac{7}{3}} c_T^{4v_T-\frac{2p}{3}-\frac{14}{3}} \underline{K}^{7+p-4v_T-2v_s}} \quad \text{(includes 6 permutations of } a, b, c), \\
Z_a^{u;\lambda_2;\lambda_3} &= \frac{c_s^{-\frac{1}{3}} c_T^{-\frac{2}{3}} \underline{K}}{32k_a^2 k_b^2 k_c^2} (k_a - k_b - k_c)(k_a + k_b - k_c)(k_a - k_b + k_c)[k_a^2 - (\lambda_2 k_b + \lambda_3 k_c)^2]^u.
\end{aligned} \tag{6.8}$$

C. Functions appearing in two scalar one tensor correlation

The functional dependence of the coefficients appearing in the context of two scalar one tensor correlation can be expressed as

$$\begin{aligned}
(\hat{V}_1)_{ij} &= \left[\frac{(k_{2i}k_{3j} + k_{3i}k_{2j})}{k_1^{v_T}(k_2k_3)^{v_s}} + \frac{(k_{1i}k_{3j} + k_{3i}k_{1j})}{k_2^{v_T}(k_1k_3)^{v_s}} + \frac{(k_{1i}k_{2j} + k_{2i}k_{1j})}{k_3^{v_T}(k_1k_2)^{v_s}} \right] \tilde{O}, \\
(\hat{V}_2)_{ij} &= c_s \left(\frac{3}{2} - v_T \right) \left[\frac{(k_{2i}k_{3j}P_{123} + k_{3i}k_{2j}P_{132})}{k_1^{v_T}(k_2k_3)^{v_s}} + \frac{(k_{1i}k_{3j}P_{213} + k_{3i}k_{1j}P_{231})}{k_2^{v_T}(k_1k_3)^{v_s}} + \frac{(k_{1i}k_{2j}P_{312} + k_{2i}k_{1j}P_{321})}{k_3^{v_T}(k_1k_2)^{v_s}} \right], \\
(\hat{V}_3)_{ij} &= c_s \left[\frac{(k_{2i}k_{3j}R_{123} + k_{3i}k_{2j}R_{132})}{k_1^{v_T}(k_2k_3)^{v_s}} + \frac{(k_{1i}k_{3j}R_{213} + k_{3i}k_{1j}R_{231})}{k_2^{v_T}(k_1k_3)^{v_s}} + \frac{(k_{1i}k_{2j}R_{312} + k_{2i}k_{1j}R_{321})}{k_3^{v_T}(k_1k_2)^{v_s}} \right], \\
(\hat{V}_4)_{ij} &= \left[k_1^2 \frac{(k_{2i}k_{3j}\tilde{R}_{123} + k_{3i}k_{2j}\tilde{R}_{132})}{k_1^{v_T}(k_2k_3)^{v_s}} + k_2^2 \frac{(k_{1i}k_{3j}\tilde{R}_{213} + k_{3i}k_{1j}\tilde{R}_{231})}{k_2^{v_T}(k_1k_3)^{v_s}} + k_3^2 \frac{(k_{1i}k_{2j}\tilde{R}_{312} + k_{2i}k_{1j}\tilde{R}_{321})}{k_3^{v_T}(k_1k_2)^{v_s}} \right], \\
(\hat{V}_5)_{ij} &= \left[k_1^2 \frac{(k_{2i}k_{3j} + k_{3i}k_{2j})}{k_1^{v_T}(k_2k_3)^{v_s}} + k_2^2 \frac{(k_{1i}k_{3j} + k_{3i}k_{1j})}{k_2^{v_T}(k_1k_3)^{v_s}} + k_3^2 \frac{(k_{1i}k_{2j} + k_{2i}k_{1j})}{k_3^{v_T}(k_1k_2)^{v_s}} \right] \tilde{O}, \\
(\hat{V}_6)_{ij} &= \left[k_1^2 \frac{(k_{2i}k_{3j}\tilde{L}_{123} + k_{3i}k_{2j}\tilde{L}_{132})}{k_1^{v_T}(k_2k_3)^{v_s}} + k_2^2 \frac{(k_{1i}k_{3j}\tilde{L}_{213} + k_{3i}k_{1j}\tilde{L}_{231})}{k_2^{v_T}(k_1k_3)^{v_s}} + k_3^2 \frac{(k_{1i}k_{2j}\tilde{L}_{312} + k_{2i}k_{1j}\tilde{L}_{321})}{k_3^{v_T}(k_1k_2)^{v_s}} \right].
\end{aligned} \tag{6.9}$$

with

$$\begin{aligned}
\tilde{O} &= \left\{ \sum_{p=1}^4 O_p \frac{\Gamma(9+p-4v_s-2v_T)}{c_s^{4v_s-\frac{2p}{3}-6} c_T^{2v_T-\frac{p}{3}-3} \underline{\underline{K}}^{9+p-4v_s-2v_T}} \right\}, \\
O_1 &= 1, \quad O_2 = i c_s^{-\frac{2}{3}} c_T^{-\frac{1}{3}} \underline{\underline{K}}, \\
O_3 &= -(k_a k_b + k_b k_c + k_c k_a), \quad O_4 = -i k_a k_b k_c, \\
P_{abc} &= \sum_{p=1}^5 m_p^{abc} \frac{\Gamma(8+p-4v_T-2v_s)}{c_s^{4v_s-\frac{2p}{3}-\frac{16}{3}} c_T^{2v_T-\frac{p}{3}-\frac{8}{3}} \underline{\underline{K}}^{8+p-4v_s-2v_T}}, \\
m_1^{abc} &= \left(\frac{3}{2} - v_T \right), \quad m_2^{abc} = c_s^{-\frac{2}{3}} c_T^{-\frac{1}{3}} \underline{\underline{K}} m_1^{abc}, \\
m_3^{abc} &= \left[\left(\frac{3}{2} - v_T \right) (k_a k_b + k_b k_c + k_c k_a) + k_a^2 \right], \quad m_4^{abc} \\
&= \left[\left(\frac{3}{2} - v_T \right) k_a k_b k_c + k_a^2 (k_b + k_c) \right], \quad m_5^{abc} = k_a^2 k_b k_c, \\
R_{abc} &= L_1 \left(\frac{3}{2} - v_T \right) \\
&\times \sum_{p=1}^5 \tilde{A}_p^{abc} \frac{\Gamma(8+p-2v_T-4v_s)}{c_s^{4v_s-\frac{2p}{3}-\frac{16}{3}} c_T^{2v_T-\frac{p}{3}-\frac{8}{3}} \underline{\underline{K}}^{8+p-2v_T-4v_s}} \\
&+ \left\{ \frac{a^2 Y_s}{t_1} \frac{(\frac{3}{2} - v_T)(\frac{3}{2} - v_s)}{k_c^2} \sum_{q=1}^6 [\hat{\mathcal{J}}_q(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^\mu \right. \\
&\times \left. \frac{\Gamma(7+p-2v_T-4v_s)}{c_s^{4v_s-\frac{2p}{3}-\frac{14}{3}} c_T^{2v_T-\frac{p}{3}-\frac{7}{3}} \underline{\underline{K}}^{7+p-2v_T-4v_s}} \right\},
\end{aligned} \tag{6.11}$$

$$\begin{aligned}
& [\hat{\mathcal{J}}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u = \left(\frac{3}{2} - \nu_s\right) \left(\frac{3}{2} - \nu_T\right), [\hat{\mathcal{J}}_2(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u = i c_s^{-\frac{2}{3}} c_T^{-\frac{1}{3}} \underline{\underline{K}} [\hat{\mathcal{J}}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u, \\
& [\hat{\mathcal{J}}_3(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u = - \left[\left(\frac{3}{2} - \nu_s\right) k_a^2 + \left(\frac{3}{2} - \nu_T\right) k_b^2 + \left(\frac{3}{2} - \nu_s\right) \left(\frac{3}{2} - \nu_T\right) \{k_a k_b + k_b k_c + k_c k_a\} \right], \\
& [\hat{\mathcal{J}}_4(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u = -i \left[\left(\frac{3}{2} - \nu_s\right) k_a^2 k_c + \left(\frac{3}{2} - \nu_T\right) k_c^2 k_a + \left(\frac{3}{2} - \nu_s\right) k_a^2 k_b \right. \\
& \quad \left. + \left(\frac{3}{2} - \nu_T\right) k_c^2 k_b + k_a k_b k_c [\hat{\mathcal{J}}_1(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u \right], \\
& [\hat{\mathcal{J}}_5(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u = \left[k_a^2 k_c^2 + \left(\frac{3}{2} - \nu_s\right) k_a^2 k_b k_c + \left(\frac{3}{2} - \nu_T\right) k_a k_b k_c^2 \right], [\hat{\mathcal{J}}_6(\vec{k}_a, \vec{k}_b, \vec{k}_c)]^u = i k_a^2 k_b k_c^2, \\
& \bar{\mathcal{A}}_1^{abc} = \left(\frac{3}{2} - \nu_T\right), \bar{\mathcal{A}}_2^{abc} = i c_s^{-\frac{2}{3}} c_T^{-\frac{1}{3}} \underline{\underline{K}} \bar{\mathcal{A}}_1^{abc}, \bar{\mathcal{A}}_3^{abc} = - \left(\frac{3}{2} - \nu_T\right) [k_a k_b + k_b k_c + k_c k_a + k_a^2], \\
& \bar{\mathcal{A}}_4^{abc} = \left[k_a k_b k_c \left(\frac{3}{2} - \nu_T\right) + k_a^2 (k_b + k_c) \right], \bar{\mathcal{A}}_5^{abc} = k_a^2 k_b k_c, \\
& \tilde{R}_{abc} = k_a^2 L_1 \tilde{O} + \frac{a^2 Y_s}{t_1} \frac{k_a^2}{k_b^2} \left(\frac{3}{2} - \nu_s\right) P_{abc}, \\
& L_{abc} = L_1^2 \tilde{O} - \frac{L_1 a^2 Y_s \left(\frac{3}{2} - \nu_s\right)}{t_1} \sum_{p=1}^5 n_q^{abc} \frac{\Gamma(8+p-4\nu_s-2\nu_T)}{c_s^{4\nu_s-\frac{2p}{3}-\frac{16}{3}} c_T^{2\nu_T-\frac{p}{3}-\frac{8}{3}} \underline{\underline{K}}^{8+p-4\nu_s-2\nu_T}} \\
& \quad + \frac{a^4 Y_s^2 \left(\frac{3}{2} - \nu_s\right)^2}{t_1^2 k_b^2 k_c^2} \sum_{r=1}^6 d_r^{abc} \frac{\Gamma(7+p-4\nu_s-2\nu_T)}{c_s^{4\nu_s-\frac{2p}{3}-\frac{14}{3}} c_T^{2\nu_T-\frac{p}{3}-\frac{7}{3}} \underline{\underline{K}}^{7+p-4\nu_s-2\nu_T}}, \\
& n_1^{abc} = \left(\frac{3}{2} - \nu_s\right) \left(\frac{1}{k_a^2} + \frac{1}{k_b^2}\right), n_2^{abc} = i c_s^{-\frac{2}{3}} c_T^{-\frac{1}{3}} \underline{\underline{K}} n_1^{abc}, \\
& n_3^{abc} = - \left[2 + \left(\frac{3}{2} - \nu_s\right) \left(\frac{k_c}{k_b} + \frac{k_b}{k_c}\right) + \left(\frac{3}{2} - \nu_s\right) k_a^2 (k_b + k_c) \left(\frac{1}{k_a^2} + \frac{1}{k_b^2}\right) \right], \\
& n_4^{abc} = -i \left\{ (k_c + k_b) + k_a \left[2 + \left(\frac{3}{2} - \nu_s\right) \left(\frac{k_c}{k_b} + \frac{k_b}{k_c}\right) \right] \right\}, n_5^{abc} = k_a (k_c + k_b), \\
& d_1^{abc} = \left(\frac{3}{2} - \nu_s\right)^2, d_2^{abc} = i c_s^{-\frac{2}{3}} c_T^{-\frac{1}{3}} \underline{\underline{K}} d_1^{abc}, d_3^{abc} = -(k_b^2 + k_c^2 + k_b k_c + k_a k_b + k_a k_c), d_6^{abc} = i k_a k_b^2 k_c^2 \\
& d_4^{abc} = -i \left[k_b^2 k_c^4 + \left(\frac{3}{2} - \nu_s\right) \{k_b k_c^2 + k_a (k_b^2 + k_c^2 + k_b k_c)\} \right], d_5^{abc} = \left[k_b^2 k_c^2 + k_a \left(k_b^2 k_c + k_b k_c^2 \left(\frac{3}{2} - \nu_s\right) \right) \right].
\end{aligned}
\tag{6.12}$$

After using the basis transformation mentioned in Eq. (3.23) we get

$$\begin{aligned}
 (\hat{V}_1)_{\lambda'} &= \left[\frac{(k_2^{\lambda'} k_3^{\lambda''} + k_3^{\lambda'} k_2^{\lambda''})}{k_1^{v_T} (k_2 k_3)^{v_s}} + \frac{(k_1^{\lambda'} k_3^{\lambda''} + k_3^{\lambda'} k_1^{\lambda''})}{k_2^{v_T} (k_1 k_3)^{v_s}} + \frac{(k_1^{\lambda'} k_2^{\lambda''} + k_2^{\lambda'} k_1^{\lambda''})}{k_3^{v_T} (k_1 k_2)^{v_s}} \right] \tilde{O}_{\delta_{\lambda', \lambda''}}, \\
 \frac{(\hat{V}_2)_{\lambda'}}{c_s \left(\frac{3}{2} - v_T \right)} &= \left[\frac{(k_2^{\lambda'} k_3^{\lambda''} P_{123} + k_3^{\lambda'} k_2^{\lambda''} P_{132})}{k_1^{v_T} (k_2 k_3)^{v_s}} + \frac{(k_1^{\lambda'} k_3^{\lambda''} P_{213} + k_3^{\lambda'} k_1^{\lambda''} P_{231})}{k_2^{v_T} (k_1 k_3)^{v_s}} + \frac{(k_1^{\lambda'} k_2^{\lambda''} P_{312} + k_2^{\lambda'} k_1^{\lambda''} P_{321})}{k_3^{v_T} (k_1 k_2)^{v_s}} \right] \delta_{\lambda', \lambda''}, \\
 (\hat{V}_3)_{\lambda'} &= c_s \left[\frac{(k_2^{\lambda'} k_3^{\lambda''} R_{123} + k_3^{\lambda'} k_2^{\lambda''} R_{132})}{k_1^{v_T} (k_2 k_3)^{v_s}} + \frac{(k_1^{\lambda'} k_3^{\lambda''} R_{213} + k_3^{\lambda'} k_1^{\lambda''} R_{231})}{k_2^{v_T} (k_1 k_3)^{v_s}} + \frac{(k_1^{\lambda'} k_2^{\lambda''} R_{312} + k_2^{\lambda'} k_1^{\lambda''} R_{321})}{k_3^{v_T} (k_1 k_2)^{v_s}} \right] \delta_{\lambda', \lambda''}, \\
 (\hat{V}_4)_{\lambda'} &= \left[k_1^2 \frac{(k_2^{\lambda'} k_3^{\lambda''} \tilde{R}_{123} + k_3^{\lambda'} k_2^{\lambda''} \tilde{R}_{132})}{k_1^{v_T} (k_2 k_3)^{v_s}} + k_2^2 \frac{(k_1^{\lambda'} k_3^{\lambda''} \tilde{R}_{213} + k_3^{\lambda'} k_1^{\lambda''} \tilde{R}_{231})}{k_2^{v_T} (k_1 k_3)^{v_s}} + k_3^2 \frac{(k_1^{\lambda'} k_2^{\lambda''} \tilde{R}_{312} + k_2^{\lambda'} k_1^{\lambda''} \tilde{R}_{321})}{k_3^{v_T} (k_1 k_2)^{v_s}} \right] \delta_{\lambda', \lambda''}, \\
 (\hat{V}_5)_{\lambda'} &= \left[k_1^2 \frac{(k_2^{\lambda'} k_3^{\lambda''} + k_3^{\lambda'} k_2^{\lambda''})}{k_1^{v_T} (k_2 k_3)^{v_s}} + k_2^2 \frac{(k_1^{\lambda'} k_3^{\lambda''} + k_3^{\lambda'} k_1^{\lambda''})}{k_2^{v_T} (k_1 k_3)^{v_s}} + k_3^2 \frac{(k_1^{\lambda'} k_2^{\lambda''} + k_2^{\lambda'} k_1^{\lambda''})}{k_3^{v_T} (k_1 k_2)^{v_s}} \right] \tilde{O}_{\delta_{\lambda', \lambda''}}, \\
 (\hat{V}_6)_{\lambda'} &= \left[k_1^2 \frac{(k_2^{\lambda'} k_3^{\lambda''} \tilde{L}_{123} + k_3^{\lambda'} k_2^{\lambda''} \tilde{L}_{132})}{k_1^{v_T} (k_2 k_3)^{v_s}} + k_2^2 \frac{(k_1^{\lambda'} k_3^{\lambda''} \tilde{L}_{213} + k_3^{\lambda'} k_1^{\lambda''} \tilde{L}_{231})}{k_2^{v_T} (k_1 k_3)^{v_s}} + k_3^2 \frac{(k_1^{\lambda'} k_2^{\lambda''} \tilde{L}_{312} + k_2^{\lambda'} k_1^{\lambda''} \tilde{L}_{321})}{k_3^{v_T} (k_1 k_2)^{v_s}} \right] \delta_{\lambda', \lambda''},
 \end{aligned} \tag{6.13}$$

where $k_i^{\lambda} = k_i$ where $i = 1, 2, 3$. Most surprisingly, the above coefficients are independent of λ due to there being no parity violation.

D. Functions appearing in three-tensor correlation

The functional dependence of the coefficients appearing in the context of three-tensor correlation can be expressed as

$$\begin{aligned}
 \Delta_{i_1 j_1 i_2 j_2 i_3 j_3}^{(1)} &= \frac{\sigma}{12} \mathcal{N}_{i_1 j_1; i j} \mathcal{N}_{i_2 j_2; j k} \mathcal{N}_{i_3 j_3; k i} c_s^3 \left(\frac{3}{2} - v_T \right)^3 [M_{123} + M_{132} + M_{213} + M_{231} + M_{312} + M_{321}], \\
 \Delta_{i_1 j_1 i_2 j_2 i_3 j_3}^{(2)} &= \frac{Y_T}{2c_T^2} \mathcal{N}_{i_1 j_1; i k} \mathcal{N}_{i_2 j_2; j l} \mathcal{N}_{i_3 j_3; i j} [k_{3k} k_{3l} + k_{2k} k_{2l} + k_{1k} k_{1l}] \mathcal{Q}, \\
 \Delta_{i_1 j_1 i_2 j_2 i_3 j_3}^{(3)} &= -\frac{Y_T}{2c_T^2} \mathcal{N}_{i_1 j_1; i_3 j_3} \mathcal{N}_{i_2 j_2; k l} [k_{3k} k_{3l} + k_{2k} k_{2l} + k_{1k} k_{1l}] \mathcal{Q}
 \end{aligned} \tag{6.14}$$

with

$$\begin{aligned}
 \mathcal{Q} &= \sum_{p=1}^4 O_p \frac{\Gamma(9+p-6v_T)}{K^{9+p-6v_T}}, \quad M_{abc} = \sum_{p=1}^7 b_p^{abc} \frac{\Gamma(6+p-6v_T)}{K^{6+p-6v_T}}, \quad b_1^{abc} = \left(\frac{3}{2} - v_T \right)^3, \quad b_2^{abc} = b_1^{abc} K, \\
 b_3^{abc} &= \left(\frac{3}{2} - v_T \right)^2 [k_a (k_b + k_c) + k_b^2 + k_c^2 + k_b k_c + k_a^2], \\
 b_4^{abc} &= \left[k_a^2 (k_b + k_c) \left(\frac{3}{2} - v_T \right) + \{k_a (k_b^2 + k_c^2 + k_b k_c) + k_b k_c (k_b + k_c)\} \left(\frac{3}{2} - v_T \right)^2 \right], \\
 b_5^{abc} &= \left[\left(\frac{3}{2} - v_T \right) \{k_a^2 (k_b^2 + k_c^2 + k_b k_c) + k_b^2 k_c^2\} + \left(\frac{3}{2} - v_T \right)^2 k_a k_b k_c (k_b + k_c) \right], \\
 b_6^{abc} &= \left(\frac{3}{2} - v_T \right) k_a k_b k_c [k_b k_c + k_a (k_b + k_c)], \quad b_7^{abc} = -k_a^2 k_b^2 k_c^2.
 \end{aligned} \tag{6.15}$$

After using the basis transformation mentioned in Eq. (3.23) the helicity dependent functions are given by

$$\begin{aligned}\Delta_{\lambda_1\lambda_2\lambda_3}^{(1)} &= \frac{\sigma}{12}\delta_{\lambda_1\lambda'}\delta_{\lambda_2\lambda''}\delta_{\lambda_3\lambda'''}c_s^3\left(\frac{3}{2}-v_T\right)^3[M_{123}^{\lambda'\lambda''\lambda'''}+M_{132}^{\lambda'\lambda''\lambda'''}+M_{213}^{\lambda'\lambda''\lambda'''}+M_{231}^{\lambda'\lambda''\lambda'''}+M_{312}^{\lambda'\lambda''\lambda'''}+M_{321}^{\lambda'\lambda''\lambda'''}], \\ \Delta_{\lambda_1\lambda_2\lambda_3}^{(2)} &= \frac{Y_T}{2c_T^2}\delta_{\lambda_1\lambda'}\delta_{\lambda_2\lambda''}\delta_{\lambda_3\lambda'''}[k_3^{\lambda'}k_3^{\lambda''}+k_2^{\lambda'}k_2^{\lambda''}+k_1^{\lambda'}k_1^{\lambda''}]\mathcal{Q}^{\lambda'''}, \\ \Delta_{\lambda_1\lambda_2\lambda_3}^{(3)} &= -\frac{Y_T}{2c_T^2}\delta_{\lambda_1\lambda'}\delta_{\lambda_2\lambda_1}\delta_{\lambda_3\lambda'''}[k_3^{\lambda'}k_3^{\lambda''}+k_2^{\lambda'}k_2^{\lambda''}+k_1^{\lambda'}k_1^{\lambda''}]\mathcal{Q},\end{aligned}\quad (6.16)$$

with

$$\begin{aligned}M_{abc}^{\lambda'\lambda''\lambda'''} &= \sum_{p=1}^7(b_p^{abc})^{\lambda'\lambda''\lambda'''}\frac{\Gamma(6+p-6v_T)}{K^{6+p-6v_T}}, \quad \mathcal{Q}^{\lambda'''} = \sum_{p=1}^4 O_p^{\lambda'''}\frac{\Gamma(9+p-6v_T)}{K^{9+p-6v_T}}, \\ (b_1^{abc})^{\lambda'\lambda''\lambda'''} &= \left(\frac{3}{2}-v_T\right)^3, \quad (b_2^{abc})^{\lambda'\lambda''\lambda'''} = (b_1^{abc})^{\lambda'\lambda''\lambda'''}K, \\ (b_3^{abc})^{\lambda'\lambda''\lambda'''} &= \left(\frac{3}{2}-v_T\right)^2[k_a^{\lambda'}(k_b^{\lambda''}+k_c^{\lambda''})+(k_b^{\lambda''})^2+(k_c^{\lambda''})^2+k_b^{\lambda''}k_c^{\lambda''}+(k_a^{\lambda'})^2], \\ (b_4^{abc})^{\lambda'\lambda''\lambda'''} &= \left[(k_a^{\lambda'})^2(k_b^{\lambda''}+k_c^{\lambda''})\left(\frac{3}{2}-v_T\right)+\{k_a^{\lambda'}((k_b^{\lambda''})^2+(k_c^{\lambda''})^2+k_b^{\lambda''}k_c^{\lambda''})+k_b^{\lambda''}k_c^{\lambda''}(k_b^{\lambda''}+k_c^{\lambda''})\}\left(\frac{3}{2}-v_T\right)^2\right], \\ (b_5^{abc})^{\lambda'\lambda''\lambda'''} &= \left[\left(\frac{3}{2}-v_T\right)\{(k_a^{\lambda'})^2((k_b^{\lambda''})^2+(k_c^{\lambda''})^2+k_b^{\lambda''}k_c^{\lambda''})+(k_b^{\lambda''}k_c^{\lambda''})^2\}+\left(\frac{3}{2}-v_T\right)^2k_a^{\lambda'}k_b^{\lambda''}k_c^{\lambda''}(k_b^{\lambda''}+k_c^{\lambda''})\right], \\ (b_6^{abc})^{\lambda'\lambda''\lambda'''} &= \left(\frac{3}{2}-v_T\right)k_a^{\lambda'}k_b^{\lambda''}k_c^{\lambda''}[k_b^{\lambda''}k_c^{\lambda''}+k_a^{\lambda'}(k_b^{\lambda''}+k_c^{\lambda''})], \quad (b_7^{abc})^{\lambda'\lambda''\lambda'''} = -(k_a^{\lambda'}k_b^{\lambda''}k_c^{\lambda''})^2, \\ O_1^{\lambda'''} &= 1, \quad O_2^{\lambda'''} = iK^{\lambda'''}, \quad O_3^{\lambda'''} = -(k_a^{\lambda'''}k_b^{\lambda'''}+k_b^{\lambda'''}k_c^{\lambda'''}+k_c^{\lambda'''}k_a^{\lambda'''}), \quad O_4^{\lambda'''} = -ik_a^{\lambda'''}k_b^{\lambda'''}k_c^{\lambda'''},\end{aligned}\quad (6.17)$$

where $k_1^{\lambda'} = \lambda' k_1$, $k_2^{\lambda''} = \lambda'' k_2$, and $k_3^{\lambda'''} = \lambda''' k_3$.

E. Functions appearing in four-scalar correlator

1. Contact interaction

The functional dependence of the momentum dependent functions appearing in the context of contact interaction of the four-scalar correlation can be expressed as

$$\begin{aligned}
G_1 &= \left(\frac{3}{2} - v_s\right)^4, \quad G_2 = i\bar{K}G_1, \quad G_3 = G_1^{\frac{3}{4}} \sum_{i=1}^4 k_i^2 + G_1 \sum_{i>j=1}^4 k_i k_j, \quad G_4 = iG_1 \sum_{i>j>m=1}^4 k_i k_j k_m + iG_1^{\frac{3}{4}} \sum_{i \neq j=1}^4 k_i^2 k_j, \\
G_5 &= \sqrt{G_1} \sum_{i>j=1}^4 k_i^2 k_j^2 + G_1^{\frac{3}{4}} \sum_{i>j>m=1}^4 k_i^2 k_j k_m + G_1 \prod_{i=1}^4 k_i, \quad G_6 = i\sqrt{G_1} \sum_{i,j,m=1}^4 k_i^2 k_j^2 k_m + i \prod_{i \neq j>m>n=1}^4 k_i^2 k_j k_m k_n, \\
G_7 &= G_1^{\frac{1}{4}} \prod_{i>j>m=1}^4 k_i^2 k_j^2 k_m^2 + \sqrt{G_1} \prod_{i<j,m<n,i \neq m,j \neq n=1}^4 k_i^2 k_j^2 k_m k_n, \quad G_8 = iG_1^{\frac{3}{4}} \prod_{i>j>m \neq n=1}^4 k_i^2 k_j^2 k_m^2 k_n, \\
G_9 &= \prod_{i=1}^4 k_i^2, \quad \bar{Z}_1 = 1, \quad \bar{Z}_2 = i\bar{K}, \quad \bar{Z}_3 = \prod_{i>j=1}^4 k_i k_j, \quad \bar{Z}_4 = \prod_{i>j>m=1}^4 k_i k_j k_m, \quad \bar{Z}_5 = \prod_{i=1}^4 k_i
\end{aligned} \tag{6.18}$$

and

$$\begin{aligned}
\bar{\mathcal{I}}(i, j; m, n) &= \left[\bar{K}^4 \sqrt{G_1} \Gamma(10 - 6v_s) + \bar{K}^3 \sqrt{G_1} (k_i + k_j + k_m + k_n) \Gamma(11 - 6v_s) \right. \\
&\quad \left. - \bar{K}^2 \left\{ k_m^2 k_n^2 - iG_1^{\frac{1}{4}} k_m k_n (k_m + k_n) - k_m k_n \sqrt{G_1} - k_i k_j \sqrt{G_1} - (k_i + k_j)(k_m + k_n) \sqrt{G_1} \right\} \Gamma(12 - 6v_s) \right. \\
&\quad \left. + \bar{K} \left\{ k_i k_j (k_m + k_n) \sqrt{G_1} - (k_i + k_j) k_m k_n \sqrt{G_1} \right\} \Gamma(13 - 6v_s) + k_m k_n \sqrt{G_1} \Gamma(14 - 6v_s) \right].
\end{aligned} \tag{6.19}$$

2. Scalar exchange

The functional dependence of the momentum dependent functions appearing in the context of scalar exchange contribution of the four-scalar correlation can be expressed as

$$\begin{aligned}
\Xi_1(k_1, k_2, k_3, k_4, k_5, k_6) &:= \frac{\left(\frac{3}{2} - v_s\right)^6}{(k_5 k_6)^{v_s}} \sum_{b=0}^6 \sum_{p=0}^6 \mathbf{S}_b(k_1, k_2, k_3) \mathbf{S}_p(k_4, k_5, k_6) \frac{(-1)^{b+p-12v_s} (i(k_4 + k_5 + k_6))^{b+p-6v_s}}{(k_4 + k_5 + k_6)^4} \\
&\quad \times \Gamma\left(\frac{3}{2} + b - 3v_s\right) \Gamma(3 + b + p - 6v_s) {}_2F_1^{\text{REG}} \left[3 + b + p - 6v_s; \frac{3}{2} + b - 3v_s; \frac{5}{2} + b - 3v_s; -\frac{(k_1 + k_2 + k_3)}{(k_4 + k_5 + k_6)} \right],
\end{aligned} \tag{6.20}$$

$$\begin{aligned}
\Xi_2(k_1, k_2, k_3, k_4, k_5, k_6) &:= \frac{\left(\frac{3}{2} - v_s\right)^2}{c_S (k_5 k_6)^{v_s}} \sum_{m=0}^4 \sum_{n=0}^4 \mathbf{E}_m(k_1, k_2, k_3) \mathbf{E}_n(k_4, k_5, k_6) \frac{(-1)^{2(m+n)-9v_s} (i(k_4 + k_5 + k_6))^{1-m-n+6v_s}}{(7 + 2m - 6v_s)(k_4 + k_5 + k_6)^8} \\
&\quad \times \Gamma(7 + m + n - 6v_s) {}_2F_1 \left[7 + m + n - 6v_s; \frac{7}{2} + m - 3v_s; \frac{9}{2} + b - 3v_s; -\frac{(k_1 + k_2 + k_3)}{(k_4 + k_5 + k_6)} \right],
\end{aligned} \tag{6.21}$$

$$\begin{aligned}
\Xi_3(k_1, k_2, k_3, k_4, k_5, k_6) &:= \frac{c_S \left(\frac{3}{2} - v_s\right)^4}{(k_5 k_6)^{v_s}} \sum_{p=0}^6 \sum_{q=0}^4 \mathbf{S}_p(k_1, k_2, k_3) \mathbf{E}_q(k_4, k_5, k_6) \frac{(-1)^{2(p+q)-12v_s+3} (i(k_4 + k_5 + k_6))^{1-p-q+6v_s}}{(k_4 + k_5 + k_6)^6} \\
&\quad \times \Gamma\left(\frac{3}{2} + p - 3v_s\right) \Gamma(5 + p + q - 6v_s) {}_2F_1^{\text{REG}} \left[5 + p + q - 6v_s; \frac{3}{2} + p - 3v_s; \frac{5}{2} + p - 3v_s; -\frac{(k_1 + k_2 + k_3)}{(k_4 + k_5 + k_6)} \right],
\end{aligned} \tag{6.22}$$

$$\begin{aligned} \Xi_4(k_1, k_2, k_3, k_4, k_5, k_6) := & \frac{c_S \left(\frac{3}{2} - \nu_s\right)^3}{(k_5 k_6)^{\nu_s}} \sum_{t=0}^4 \sum_{r=0}^6 \mathbf{E}_t(k_1, k_2, k_3) \mathbf{S}_r(k_4, k_5, k_6) \frac{(-1)^{2(t+r)-12\nu_s+3} (i(k_4 + k_5 + k_6))^{1-t-r+6\nu_s}}{(k_4 + k_5 + k_6)^6} \\ & \times \Gamma\left(\frac{3}{2} + t - 3\nu_s\right) \Gamma(5 + t + r - 6\nu_s) {}_2F_1^{\text{REG}}\left[5 + t + r - 6\nu_s; \frac{3}{2} + t - 3\nu_s; \frac{5}{2} + t - 3\nu_s; -\frac{(k_1 + k_2 + k_3)}{(k_4 + k_5 + k_6)}\right], \end{aligned} \quad (6.23)$$

where we use the *regularized hypergeometric function* defined as ${}_2F_1^{\text{REG}}[a; b; c; d] = \frac{{}_2F_1[a; b; c; d]}{\Gamma[c]}$. Additionally here we define two new sets of momentum dependent functions given by

$$\begin{aligned} \mathbf{S}_0(k_a, k_b, k_c) &= \left(\frac{3}{2} - \nu_s\right)^3, \mathbf{S}_1(k_a, k_b, k_c) = -i(k_a + k_b + k_c) \left(\frac{3}{2} - \nu_s\right)^3, \\ \mathbf{S}_2(k_a, k_b, k_c) &= -\left(\frac{3}{2} - \nu_s\right)^2 \left[(k_a^2 + k_b^2) + \left(\frac{3}{2} - \nu_s\right) k_a k_b \right] - k_c(k_a + k_b) \left(\frac{3}{2} - \nu_s\right)^3 - k_c^2 \left(\frac{3}{2} - \nu_s\right)^2, \\ \mathbf{S}_3(k_a, k_b, k_c) &= i k_a k_b (k_a + k_b) \left(\frac{3}{2} - \nu_s\right)^2 + i k_c \left(\frac{3}{2} - \nu_s\right)^2 \left[(k_a^2 + k_b^2) + \left(\frac{3}{2} - \nu_s\right) k_a k_b \right] + i k_c^2 (k_a + k_b) \left(\frac{3}{2} - \nu_s\right)^2, \\ \mathbf{S}_4(k_a, k_b, k_c) &= k_a^2 k_b^2 \left(\frac{3}{2} - \nu_s\right)^2 + k_a k_b k_c (k_a + k_b) \left(\frac{3}{2} - \nu_s\right)^2 + \left(\frac{3}{2} - \nu_s\right) k_c^2 \left[(k_a^2 + k_b^2) + \left(\frac{3}{2} - \nu_s\right) k_a k_b \right], \\ \mathbf{S}_5(k_a, k_b, k_c) &= -i k_a^2 k_b^2 k_c \left(\frac{3}{2} - \nu_s\right) - i k_a k_b k_c^2 (k_a + k_b) \left(\frac{3}{2} - \nu_s\right), \mathbf{S}_6(k_a, k_b, k_c) = -k_a^2 k_b^2 k_c^2, \\ \mathbf{E}_0(k_a, k_b, k_c) &= \left(\frac{3}{2} - \nu_s\right), \mathbf{E}_1(k_a, k_b, k_c) = -i(k_a + k_b + k_c) \left(\frac{3}{2} - \nu_s\right), \mathbf{E}_2(k_a, k_b, k_c) = -k_a k_b \left(\frac{3}{2} - \nu_s\right) \\ &- k_a(k_a + k_b) \left(\frac{3}{2} - \nu_s\right) - k_a^2, \mathbf{E}_3(k_a, k_b, k_c) = i k_a k_b k_c \left(\frac{3}{2} - \nu_s\right) + i(k_a + k_b) k_a^2, \mathbf{E}_4(k_a, k_b, k_c) = k_a^2 k_b k_c, \end{aligned} \quad (6.24)$$

where the superscript indices of the momentum are $a = (1, 4)$, $b = (2, 5)$, and $c = (3, 6)$.

3. Graviton exchange

In this context the divergence free contributions of the momentum dependent functions appearing in the context of graviton exchange can be written as

$$\begin{aligned} \hat{v}_{abcd} + \hat{v}_{cdab} &= \frac{k_a + k_b}{U_{cd}^2} \left[\frac{1}{2} (U_{cd} + k_{ab}) (U_{cd}^2 - 2D_{cd}) + k_{ab}^2 (k_c + k_d) \right] + (a, b \leftrightarrow c, d) \\ &+ \frac{k_a k_b}{\bar{K}} \left[\frac{D_{cd}}{U_{cd}} - k_{ab} + \frac{k_{ab}}{U_{ab}} \left(k_c k_d - k_{ab} \frac{D_{cd}}{U_{cd}} \right) \left(\frac{1}{\bar{K}} + \frac{1}{U_{ab}} \right) \right] + (a, b \leftrightarrow c, d) \\ &- \frac{k_{ab}}{U_{ab} U_{cd} \bar{K}} \left[D_{ab} D_{cd} + 2k_{ab}^2 \left(\prod_a k_a \right) \left(\frac{1}{\bar{K}^2} + \frac{1}{U_{ab} U_{cd}} + \frac{k_{ab}}{\bar{K} U_{ab} U_{cd}} \right) \right], \end{aligned} \quad (6.25)$$

where we define $U_{ab} \equiv k_a + k_b + k_{ab}$, $D_{ab} \equiv (k_a + k_b) k_{ab} + k_a k_b$.

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